

CSC321

Introduction to Neural Networks and Machine Learning

Lecture 1: What are neural networks?

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Lecture slides are available at
www.cs.toronto.edu/~hinton

What is Machine Learning?

- It is very hard to write programs that solve problems like recognizing a face.
 - We don't know what program to write because we don't know how its done.
 - Even if we had a good idea about how to do it, the program might be horrendously complicated.
- Instead of writing a program by hand, we collect lots of examples that specify the correct output for a given input.
- A machine learning algorithm then takes these examples and produces a program that does the job.
 - The program produced by the learning algorithm may look very different from a typical hand-written program. It may contain millions of numbers.
 - If we do it right, the program works for new cases as well as the ones we trained it on.

It is very hard to say what makes a 2

0 0 0 1 1 1 1 1 1 2

2 2 2 2 2 2 2 3 3 3

3 4 4 4 4 4 5 5 5 5

6 6 7 7 7 7 8 8 8

9 9 9 9 9 9 9 9 9

Some examples of tasks that are best solved by using a learning algorithm

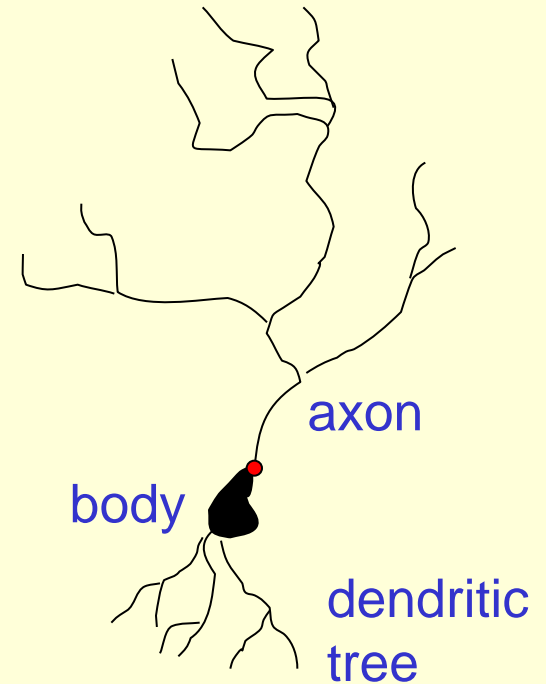
- Recognizing patterns:
 - Facial identities or facial expressions
 - Handwritten or spoken words
- Recognizing anomalies:
 - Unusual sequences of credit card transactions
 - Unusual patterns of sensor readings in a nuclear power plant
- Prediction:
 - Future stock prices
 - Future currency exchange rates

The goals of neural computation

- To understand how the brain actually works
 - Its very big and very complicated and made of yukky stuff that dies when you poke it around
- To understand a new style of computation
 - Inspired by neurons and their adaptive connections
 - Very different style from sequential computation
 - should be good for things that brains are good at (e.g. vision)
 - Should be bad for things that brains are bad at (e.g. 23 x 71)
- To solve practical problems by developing novel learning algorithms
 - Learning algorithms can be very useful even if they have nothing to do with how the brain works

A typical cortical neuron

- Gross physical structure:
 - There is one axon that branches
 - There is a dendritic tree that collects input from other neurons
- Axons typically contact dendritic trees at synapses
 - A spike of activity in the axon causes charge to be injected into the post-synaptic neuron
- Spike generation:
 - There is an **axon hillock** that generates outgoing spikes whenever enough charge has flowed in at synapses to depolarize the cell membrane

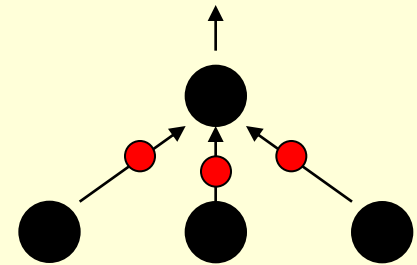


Synapses

- When a spike travels along an axon and arrives at a synapse it causes vesicles of transmitter chemical to be released
 - There are several kinds of transmitter
- The transmitter molecules diffuse across the synaptic cleft and bind to receptor molecules in the membrane of the post-synaptic neuron thus changing their shape.
 - This opens up holes that allow specific ions in or out.
- The effectiveness of the synapse can be changed
 - vary the number of vesicles of transmitter
 - vary the number of receptor molecules.
- Synapses are slow, but they have advantages over RAM
 - Very small
 - They adapt using locally available signals (but how?)

How the brain works

- Each neuron receives inputs from other neurons
 - Some neurons also connect to receptors
 - Cortical neurons use spikes to communicate
 - The timing of spikes is important
- The effect of each input line on the neuron is controlled by a synaptic weight
 - The weights can be positive or negative
- The synaptic weights **adapt** so that the whole network learns to perform useful computations
 - Recognizing objects, understanding language, making plans, controlling the body
- You have about 10^{11} neurons each with about 10^3 weights
 - A huge number of weights can affect the computation in a very short time. Much better bandwidth than a computer.



Modularity and the brain

- Different bits of the cortex do different things.
 - Local damage to the brain has specific effects
 - Specific tasks increase the blood flow to specific regions.
- But cortex looks pretty much the same all over.
 - Early brain damage makes functions relocate
- Cortex is made of general purpose stuff that has the ability to turn into special purpose hardware in response to experience.
 - This gives rapid parallel computation plus flexibility.
 - Conventional computers get flexibility by having stored programs, but this requires very fast central processors that perform large computations sequentially.

Idealized neurons

- To model things we have to idealize them (e.g. atoms)
 - Idealization removes complicated details that are not essential for understanding the main principles
 - Allows us to apply mathematics and to make analogies to other, familiar systems.
 - Once we understand the basic principles, its easy to add complexity to make the model more faithful
- It is often worth understanding models that are known to be wrong (but we mustn't forget that they are wrong!)
 - E.g. neurons that communicate real values rather than discrete spikes of activity.

Linear neurons

- These are simple but computationally limited
 - If we can make them learn we **may** get insight into more complicated neurons

$$y = b + \sum_i x_i w_i$$

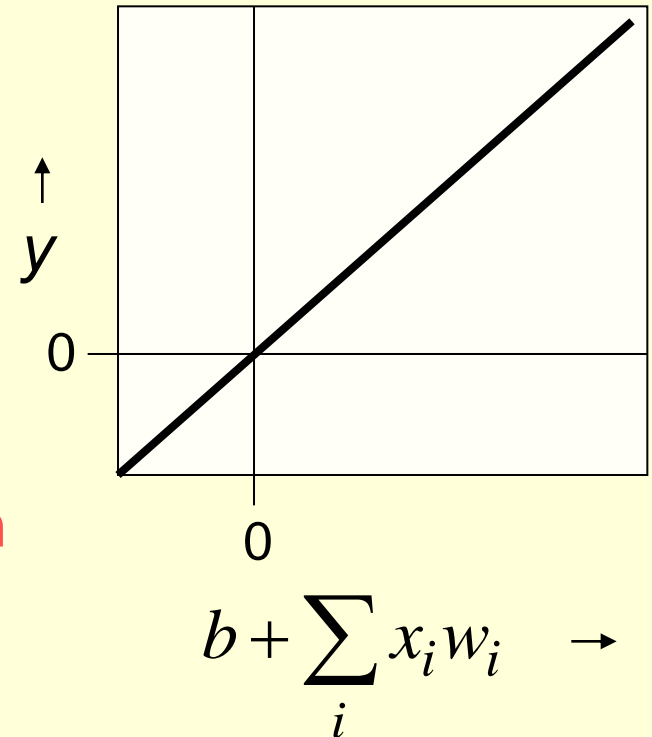
output

bias

i th input

weight on i th input

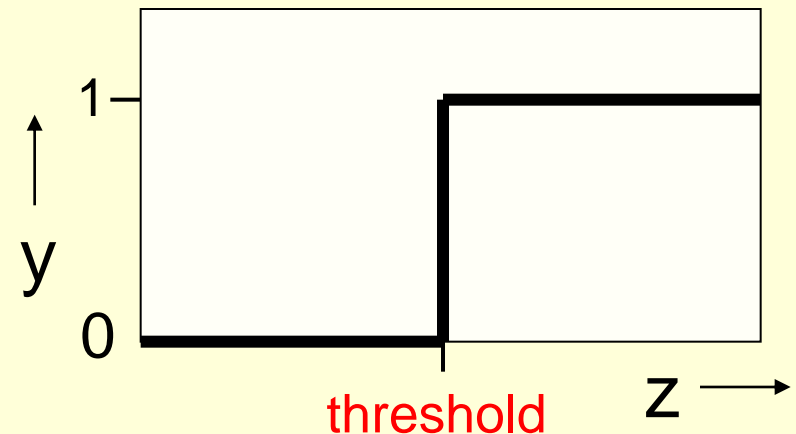
index over input connections



Binary threshold neurons

- McCulloch-Pitts (1943): **influenced Von Neumann!**
 - First compute a weighted sum of the inputs from other neurons
 - Then send out a fixed size spike of activity if the weighted sum exceeds a threshold.
 - McCulloch & Pitts: each spike is like the truth value of a proposition and each neuron combines truth values to compute the truth value of another proposition.

$$z = \sum_i x_i w_i$$
$$y = \begin{cases} 1 & \text{if } z \geq \theta \\ 0 & \text{otherwise} \end{cases}$$



Linear threshold neurons

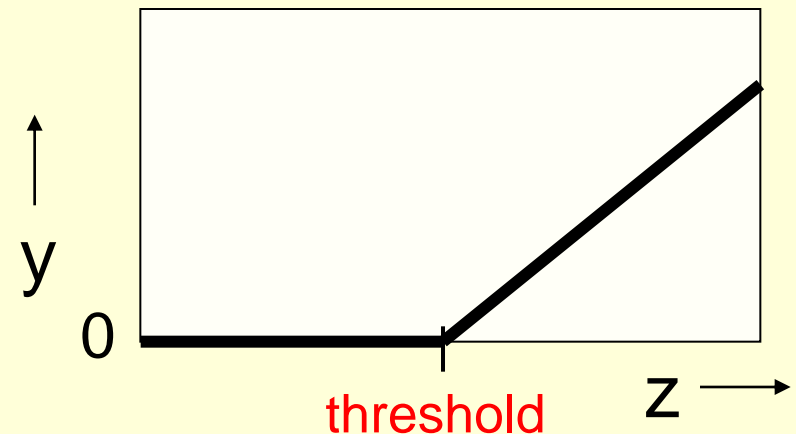
These have a confusing name.

They compute a **linear** weighted sum of their inputs

The output is a **non-linear** function of the total input

$$z_j = b_j + \sum_i x_i w_{ij}$$

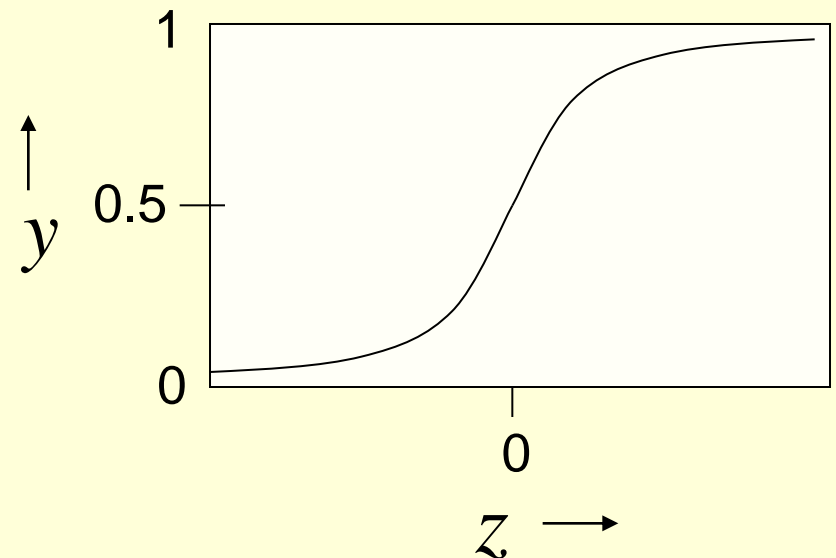
$$y_j = \begin{cases} z_j & \text{if } z_j \geq 0 \\ 0 & \text{otherwise} \end{cases}$$



Sigmoid neurons

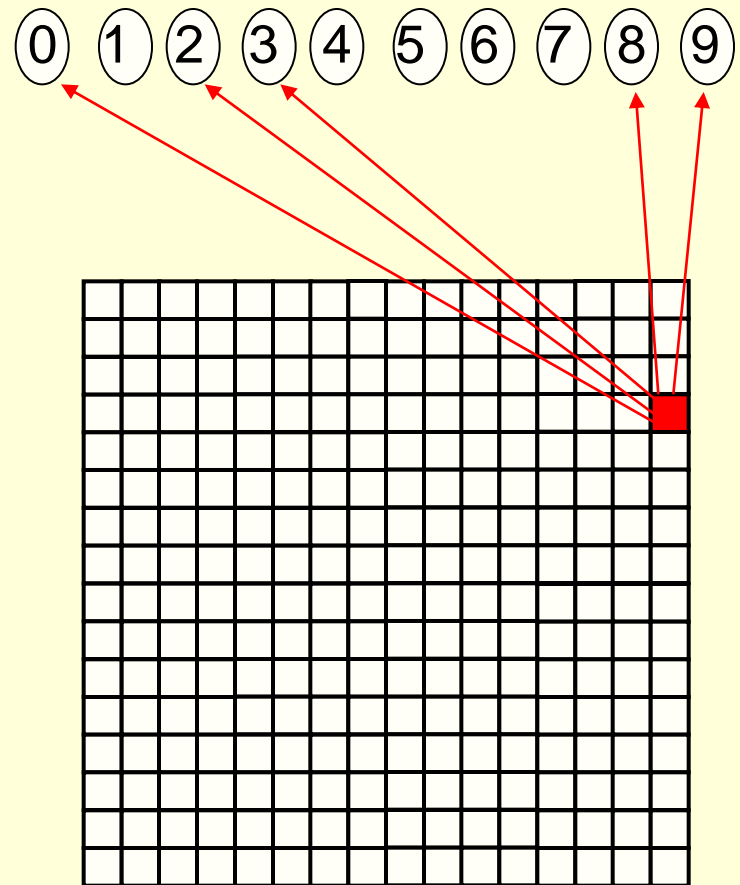
- These give a real-valued output that is a smooth and bounded function of their total input.
 - Typically they use the logistic function
 - They have nice derivatives which make learning easy (see lecture 3).
- If we treat y as a **probability** of producing a spike, we get stochastic binary neurons.

$$z = b + \sum_i x_i w_i$$
$$y = \frac{1}{1 + e^{-z}}$$

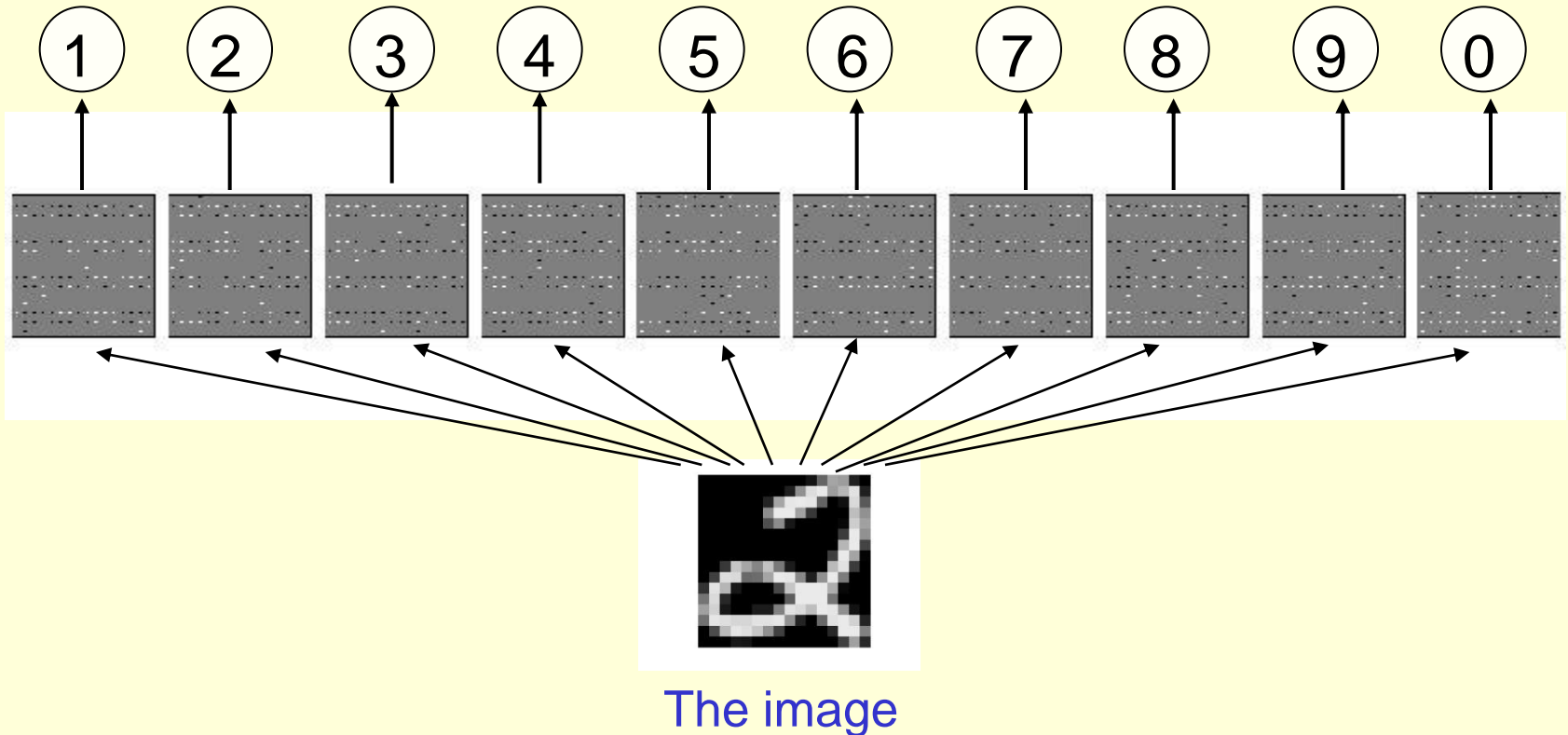


A very simple way to recognize handwritten shapes

- Consider a neural network with two layers of neurons.
 - neurons in the top layer represent known shapes.
 - neurons in the bottom layer represent pixel intensities.
- A pixel gets to vote if it has ink on it.
 - Each inked pixel can vote for several different shapes.
- The shape that gets the most votes wins.

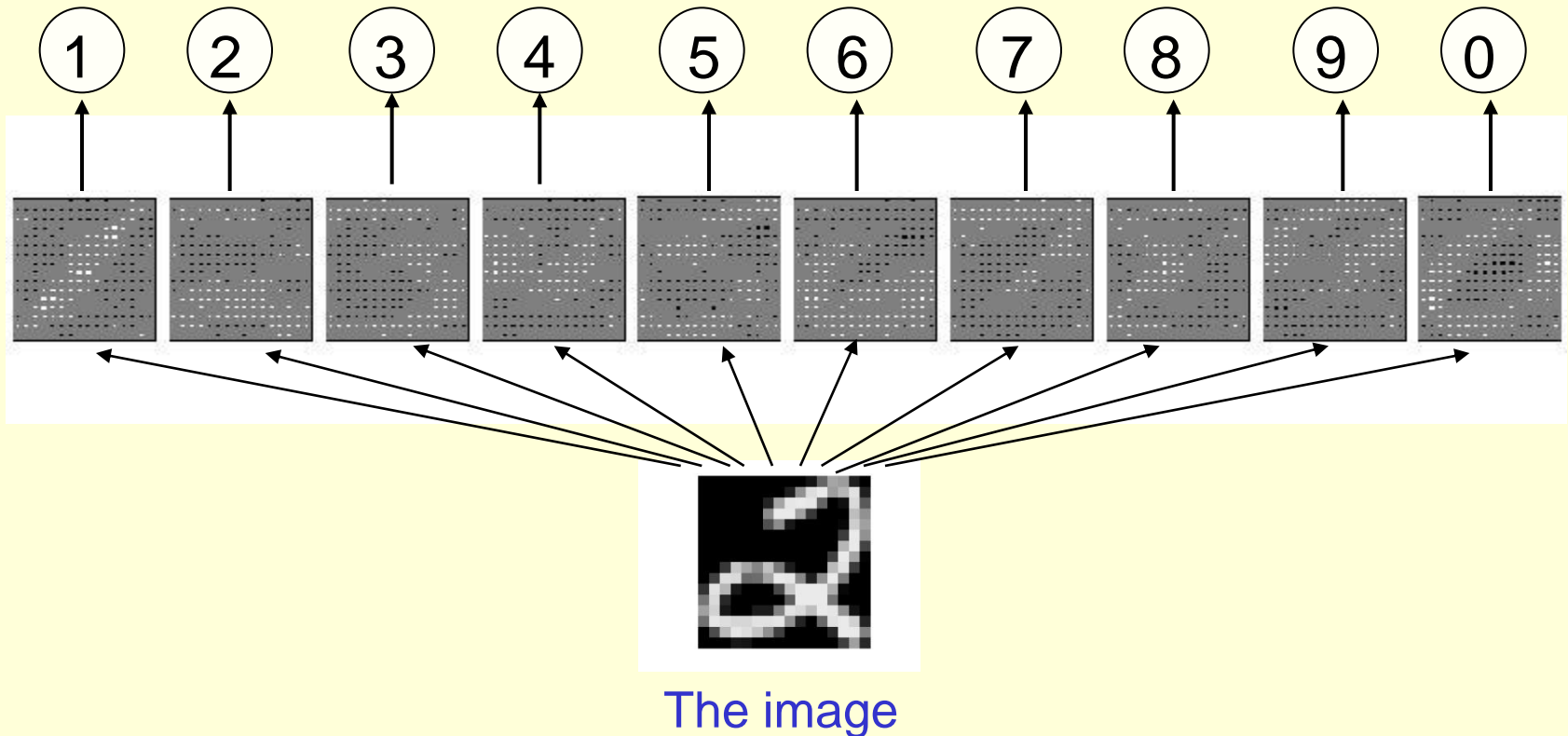


How to learn the weights



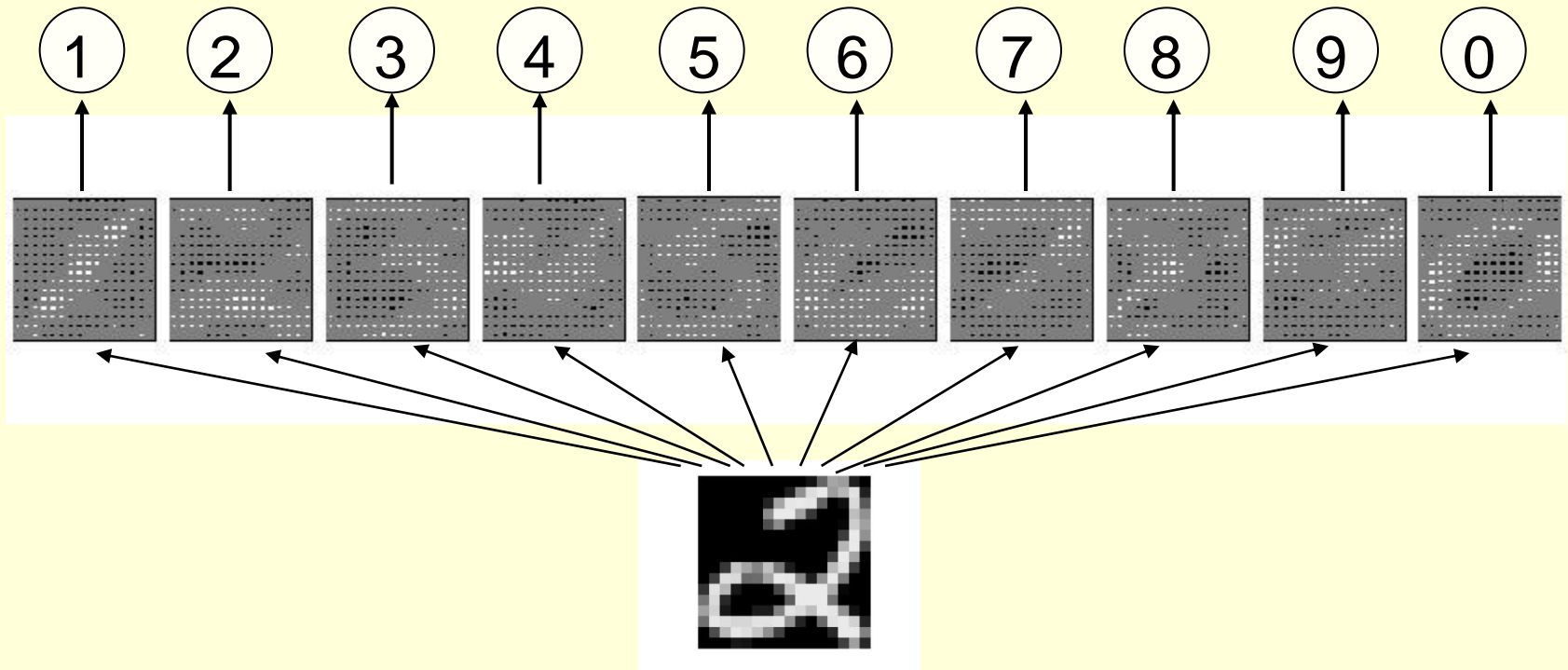
Show the network an image and **increment** the weights from active pixels to the correct class.

Then **decrement** the weights from active pixels to whatever class the network guesses.



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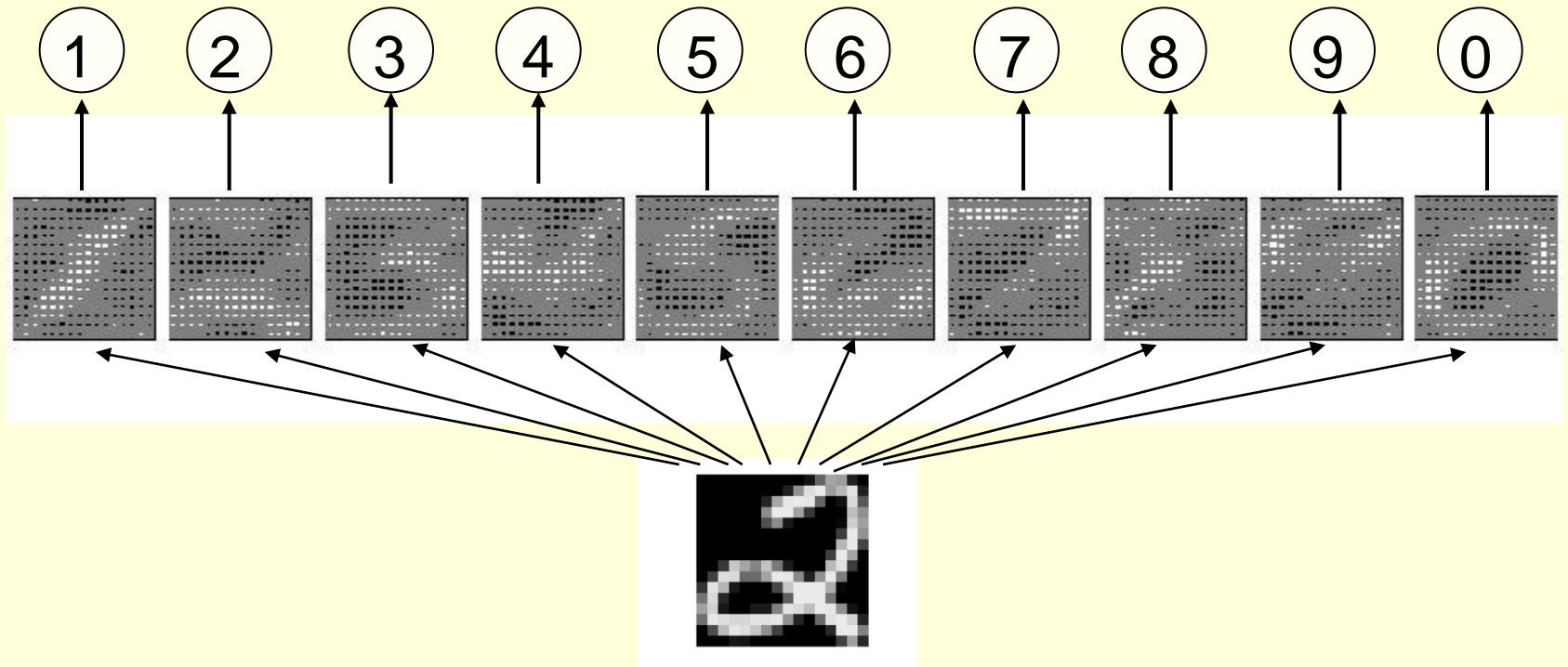
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The image

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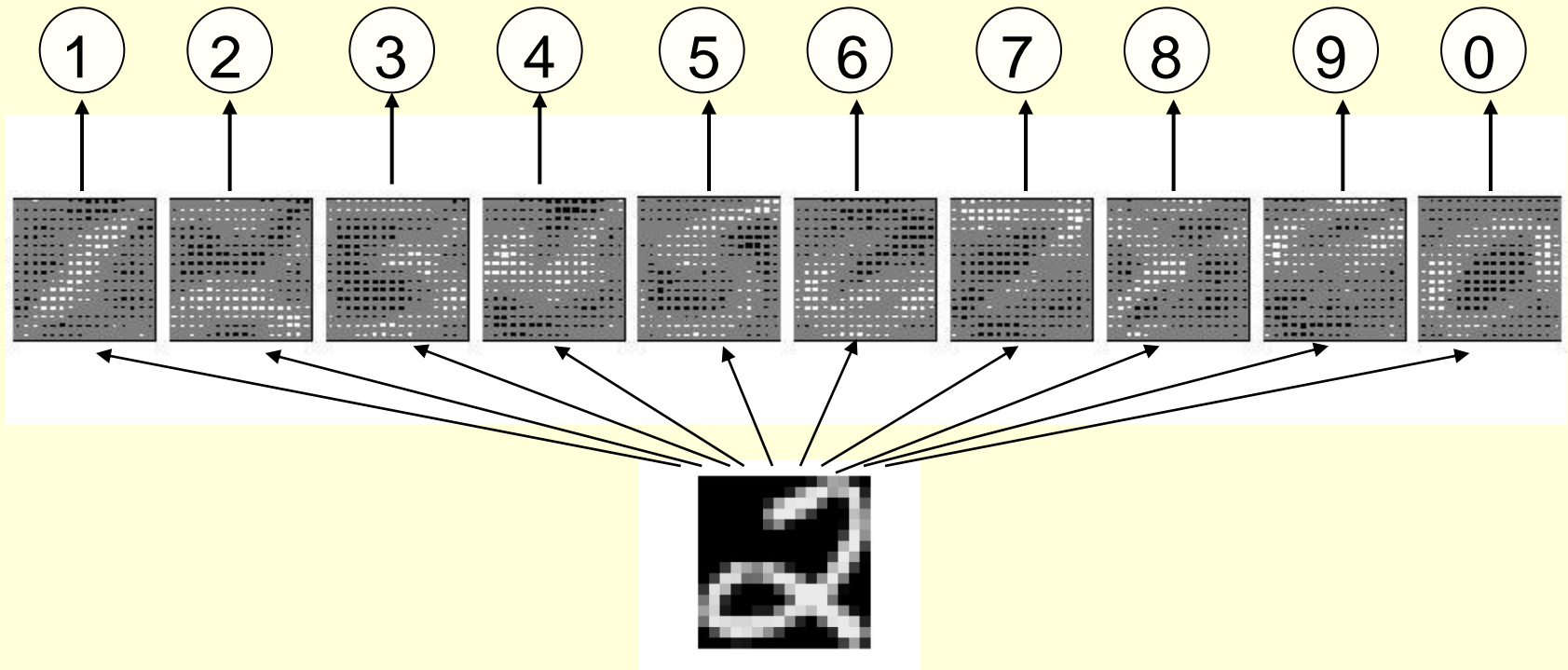
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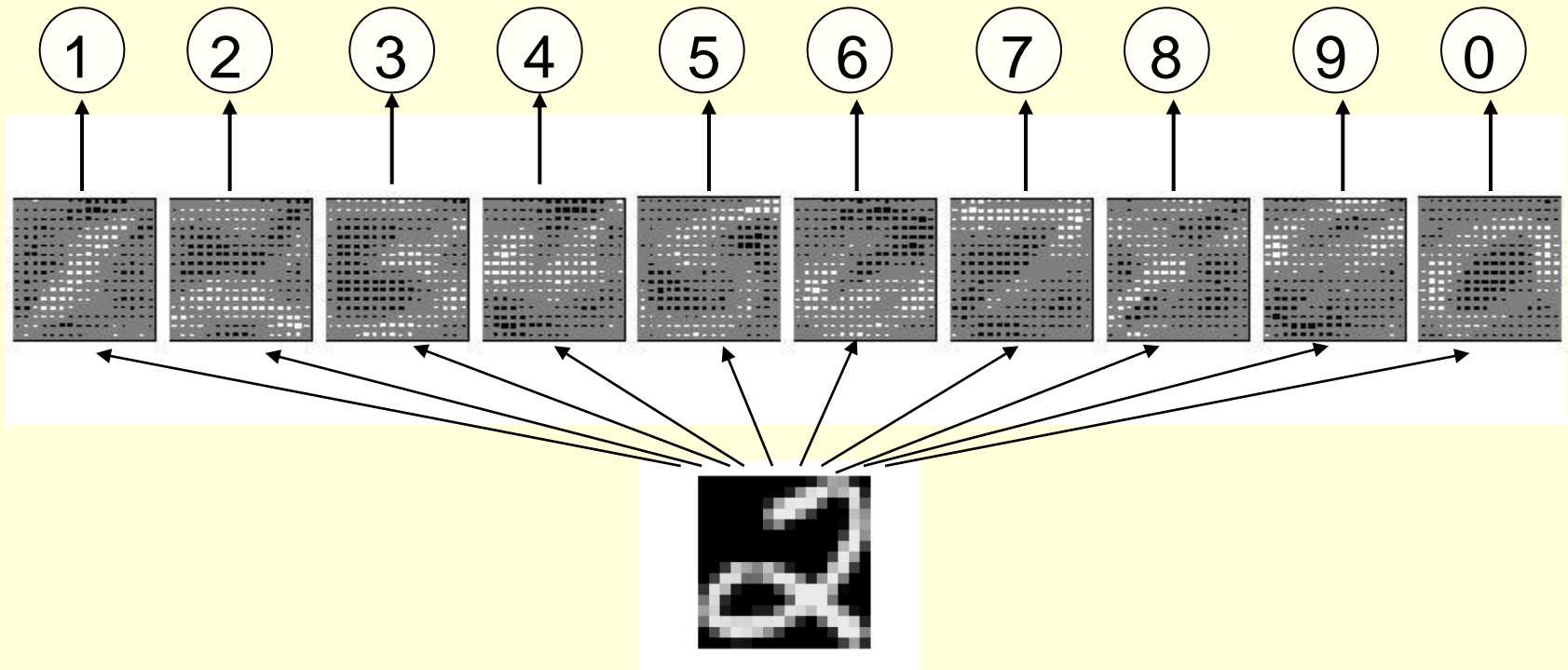
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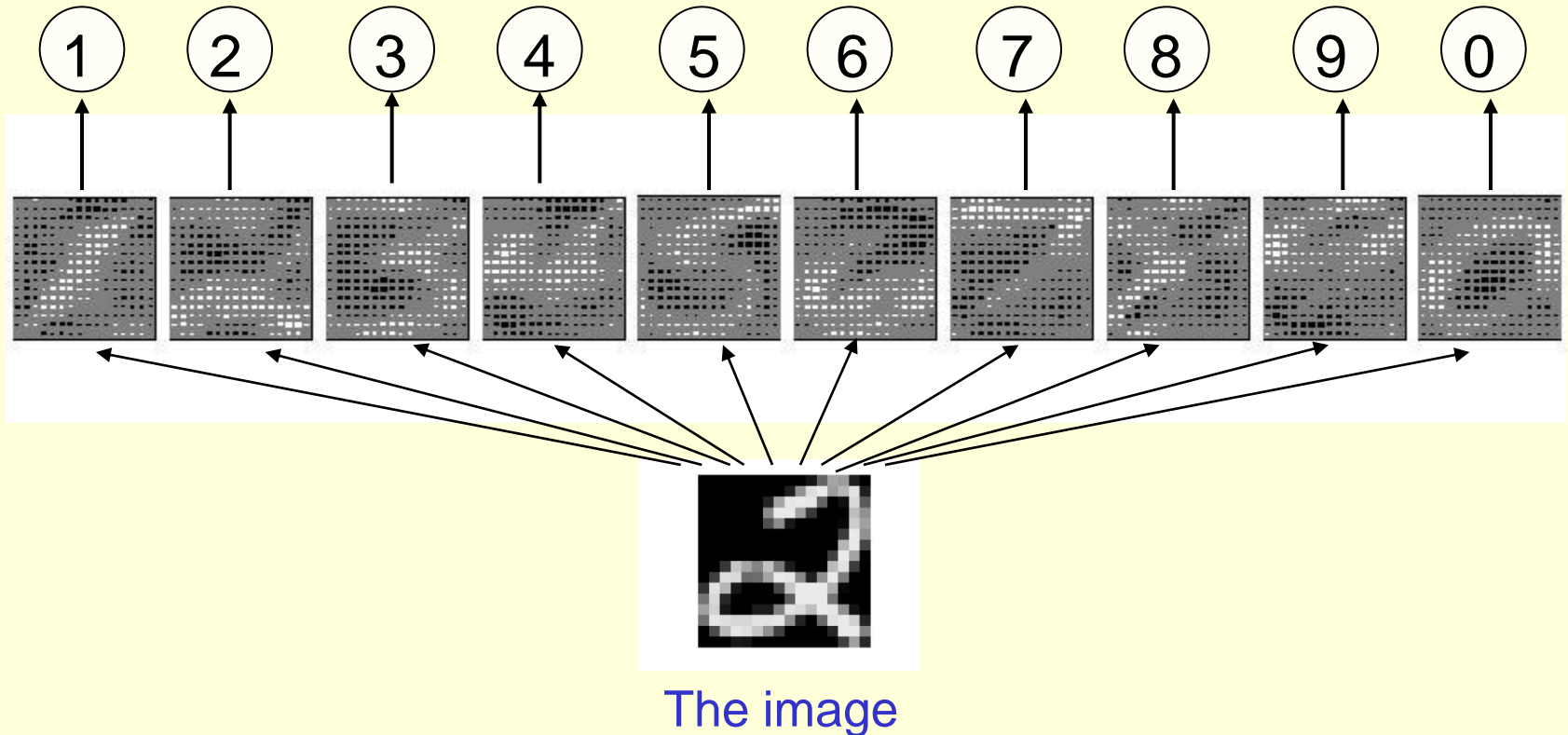


The image

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The learned weights



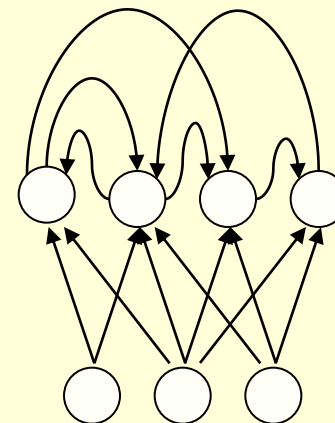
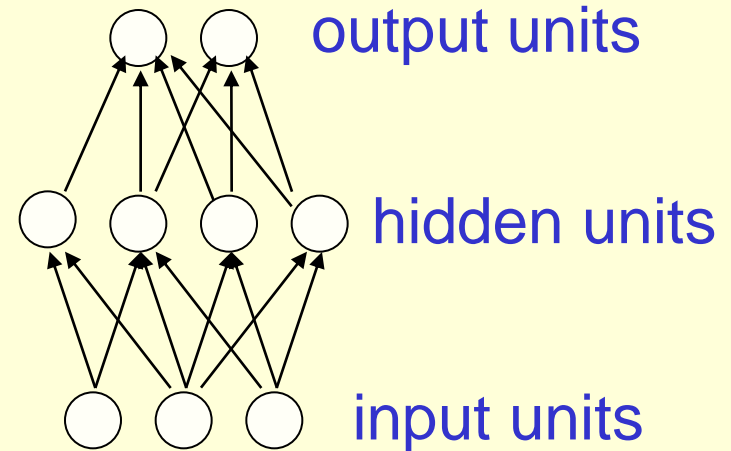
The precise details of the learning algorithm will be explained in future lectures.

Why the simple system does not work

- A two layer network with a single winner in the top layer is equivalent to having a rigid template for each shape.
 - The winner is the template that has the biggest overlap with the ink.
- The ways in which shapes vary are much too complicated to be captured by simple template matches of whole shapes.
 - To capture all the allowable variations of a shape we need to learn the features that it is composed of.

Types of connectivity

- Feedforward networks
 - These compute a series of transformations
 - Typically, the first layer is the input and the last layer is the output.
- Recurrent networks
 - These have directed cycles in their connection graph. They can have complicated dynamics.
 - More biologically realistic.



Types of learning task

- Supervised learning
 - Learn to predict output when given input vector
 - Who provides the correct answer?
- Reinforcement learning
 - Learn action to maximize payoff
 - Not much information in a payoff signal
 - Payoff is often delayed
- Unsupervised learning
 - Create an internal representation of the input e.g. form clusters; extract features
 - How do we know if a representation is good?