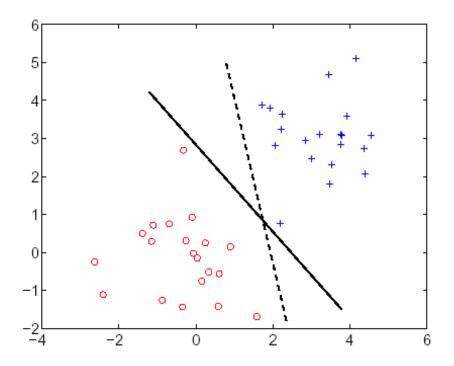
Lecture 20: Support Vector Machines

Linear Classification

- Binary classification problem: we assign labels $y \in \{-1, 1\}$ to input data x.
- Linear classifier: $y = \text{sign}(\mathbf{w} \cdot \mathbf{x} + w_0)$ and its decision surface is a hyperplane defined by $\mathbf{w} \cdot \mathbf{x} + w_0 = 0$.
- Linearly separable: we can find a linear classifier so that all the training examples are classified correctly.

$$y_i[\mathbf{w} \cdot \mathbf{x}_i + w_0] > 0, \quad \forall i = 1, ..., n$$



Perceptrons

ullet Find line that separates input patterns so that output $o=\pm 1$ on one side, o=-1 on other, and these match target values y

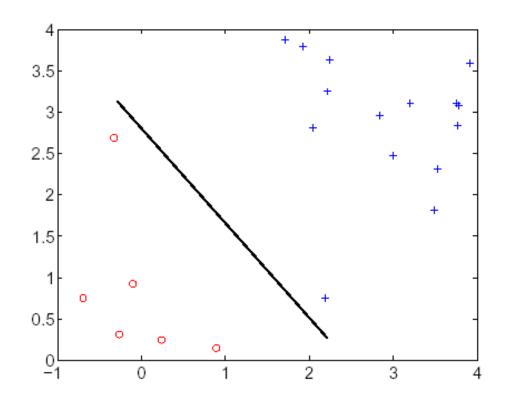
$$o(\mathbf{x}) = \operatorname{sign}(\mathbf{w} \cdot \mathbf{x} + w_0) = ?y(\mathbf{x})$$

rewrite – for every training example *i*:

$$y_i(\mathbf{w} \cdot \mathbf{x}_i + w_0) > 0$$

- We can adjust weights $\{w, w_0\}$ by Perceptron learning rule, which guarantees to converge to the correct solution in the *linear separable* case.
- Problem: which solution will has the best generalization?

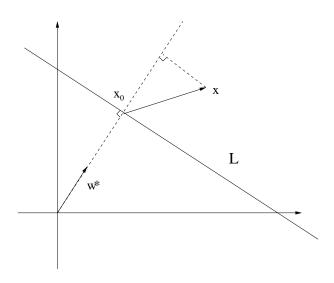
Geometrical View of Linear Classifiers



- Margin: minimal gap between classes and decision boundary.
- Answer: The linear decision surface with the maximal *margin*.

Geometric Margin

Some Vector Algebra:



- Any two points x_1 and x_2 lying in L, we have $\mathbf{w} \cdot (\mathbf{x}_1 \mathbf{x}_2) = 0$, which implies $\mathbf{w}^* = \mathbf{w}/||\mathbf{w}||$ is the unit vector normal to the surface of L.
 - Any point \mathbf{x}_0 in L, $\mathbf{w} \cdot \mathbf{x}_0 = -w_0$.
 - The signed distance of x to L is given by

$$\mathbf{w}^* \cdot (\mathbf{x} - \mathbf{x}_0) = \frac{1}{||\mathbf{w}||} (\mathbf{w} \cdot \mathbf{x} + w_0)$$

- Geometric margin of (\mathbf{x}_i, y_i) w.r.t L: $\gamma_i = y_i \frac{1}{||\mathbf{w}||} (\mathbf{w} \cdot \mathbf{x}_i + w_0)$.
- Geometric margin of $\{(\mathbf{x}_i, y_i)_{i=1}^n\}$ w.r.t L: $\min_i \gamma_i$.

Linear SVM Classifier

Linear SVM maximizes the geometric margin of training dataset:

$$\max_{\mathbf{w}, w_0} C$$

$$s.t. \quad y_i \frac{1}{||\mathbf{w}||} (\mathbf{w} \cdot \mathbf{x}_i + w_0) \ge C, \quad i = 1, ..., n$$

$$(1)$$

• For any solution satisfying the constraints, any positively scaled multiple satisfies them too. So arbitrarily setting $||\mathbf{w}|| = 1/C$, we can formulate linear SVM as: $(\min ||x|| \Leftrightarrow \min 1/2||x||^2)$

$$\min_{\mathbf{w}, w_0} \frac{1}{2} ||\mathbf{w}||^2$$
s.t. $y_i(\mathbf{w} \cdot \mathbf{x}_i + w_0) \ge 1, \quad i = 1, ..., n$ (2)

• With this setting, we define a margin around the linear decision boundary with thickness $1/||\mathbf{w}||$.

Solution to Linear SVM

 We can convert the contrained minimization to an unconstrained optimization problem by representing the constraints as penality terms:

$$\min_{\mathbf{w}, w_0} \frac{1}{2} ||\mathbf{w}||^2 + \text{penality term}$$

• For data (\mathbf{x}_i, y_i) , use the following penality term:

$$\{ \begin{array}{l} 0, y_i(\mathbf{w} \cdot \mathbf{x}_i + w_0) \ge 1 \\ \infty, \text{otherwise} \end{array} \} = \max_{\alpha_i \ge 0} \alpha_i (1 - y_i[w_0 + \mathbf{w} \cdot \mathbf{x}_i])$$

Rewrite the minimization problem

$$\min_{\mathbf{w}, w_0} \left\{ \frac{1}{2} ||\mathbf{w}||^2 + \sum_{i=1}^n \max_{\alpha_i \ge 0} \alpha_i (1 - y_i [w_0 + \mathbf{w} \cdot \mathbf{x}_i]) \right\}
= \min_{\mathbf{w}, w_0} \max_{\{\alpha_i \ge 0\}} \left\{ \frac{1}{2} ||\mathbf{w}||^2 + \sum_{i=1}^n \alpha_i (1 - y_i [w_0 + \mathbf{w} \cdot \mathbf{x}_i]) \right\}$$
(3)

• $\{\alpha_i\}$'s are called the *Lagrange multipliers*.

Solution to Linear SVM (cont'd)

• We can swap 'max' and 'min':

$$\min_{\mathbf{w}, w_0} \max_{\{\alpha_i \ge 0\}} \left\{ \frac{1}{2} ||\mathbf{w}||^2 + \sum_{i=1}^n \alpha_i (1 - y_i [w_0 + \mathbf{w} \cdot \mathbf{x}_i]) \right\} \\
= \max_{\{\alpha_i \ge 0\}} \min_{\mathbf{w}, w_0} \left\{ \frac{1}{2} ||\mathbf{w}||^2 + \sum_{i=1}^n \alpha_i (1 - y_i [w_0 + \mathbf{w} \cdot \mathbf{x}_i]) \right\} \\
\underbrace{J(\mathbf{w}, w_0; \alpha)} \tag{4}$$

• We first minimize $J(\mathbf{w}, w_0; \alpha)$ w.r.t $\{\mathbf{w}, w_0\}$ for any fixed setting of the Lagrange multipliers:

$$\frac{\partial}{\partial \mathbf{w}} J(\mathbf{w}, w_0; \alpha) = \mathbf{w} - \sum_{i=1}^{n} \alpha_i y_i \mathbf{x}_i = 0$$

$$\frac{\partial}{\partial w_0} J(\mathbf{w}, w_0; \alpha) = -\sum_{i=1}^{n} \alpha_i y_i = 0$$
(5)

$$\frac{\partial}{\partial w_0} J(\mathbf{w}, w_0; \alpha) = -\sum_{i=1}^n \alpha_i y_i = 0$$
 (6)

Solution to Linear SVM (cont'd)

• Substitute (5) and (6) back to $J(\mathbf{w}, w_0; \alpha)$:

$$\max_{\{\alpha_i \geq 0\}} \min_{\mathbf{w}, w_0} \left\{ \frac{1}{2} ||\mathbf{w}||^2 + \sum_{i=1}^n \alpha_i (1 - y_i [w_0 + \mathbf{w} \cdot \mathbf{x}_i]) \right\}$$

$$= \max_{\substack{\alpha_i \geq 0 \\ \sum_i \alpha_i y_i = 0}} \left\{ \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n y_i y_j \alpha_i \alpha_j (\mathbf{x}_i \cdot \mathbf{x}_j) \right\}$$

$$(7)$$

- Finally, we transform the original linear SVM training to a quadratic programming problem (7), which has the unique optimal solution.
- We can find the optimal setting of the Lagrange multipliers $\{\hat{\alpha}_i\}$, then solve the optimal weights $\{\hat{\mathbf{w}}, \hat{w}_0\}$.
- Essentially, we transform the primal problem to its dual form. Why should we do this?

Summary of Linear SVM

- Binary and linear separable classfication.
- Linear classifier with maximal margin.
- Training SVM by maximizing

$$\sum_{i=1}^{n} \alpha_i - \frac{1}{2} \sum_{i,j=1}^{n} y_i y_j \alpha_i \alpha_j (\mathbf{x}_i \cdot \mathbf{x}_j)$$

subject to $\alpha_i \geq 0$ and $\sum_i \alpha_i y_i = 0$.

- Weights $\hat{\mathbf{w}} = \sum_{i=1}^{n} \hat{\alpha}_i y_i \mathbf{x}_i$.
- Only a small subset of $\hat{\alpha}_i$'s will be nonzero and the corresponding data \mathbf{x}_i 's are called *support vectors*.
- Prediction on a new example x is the sign of

$$\hat{w}_0 + \mathbf{x} \cdot \hat{\mathbf{w}} = \hat{w}_0 + \mathbf{x} \cdot (\sum_{i=1}^n \hat{\alpha}_i y_i \mathbf{x}_i) = \hat{w}_0 + \sum_{i \in SV} \hat{\alpha}_i y_i (\mathbf{x} \cdot \mathbf{x}_i)$$