

## Lecture 1

*Aleksandar Nikolov*

## 1 Uniform Sets of Points

We start with one of the classical geometric discrepancy questions: “What is the most uniform set of  $n$  points in the unit square  $[0, 1]^2$ ?” This is, of course, not a well-posed question and we need to make it more precise before we can give a definite answer.

Let us start from the analogous continuous question: “What is the uniform *probability measure* on the unit square  $[0, 1]^2$ ?” In a certain sense, the unique answer to this question is the Lebesgue measure  $\lambda^2$  restricted to the square, i.e. the measure that assigns every measurable set  $S \subseteq [0, 1]^2$  its area. For instance, one natural property to ask of a “uniform” measure is that it is translation invariant. Since a translation may take us out of the square, let us look instead at translation with wrap-around, i.e. a translation by vector  $u \in \mathbb{R}^2$  maps a point  $x \in [0, 1]^2$  to  $((x_1 + u_1) \bmod 1, (x_2 + u_2) \bmod 1)$ , i.e. to the point whose coordinates are the fractional parts of the coordinates of  $x + u$ . Then the Lebesgue measure is the unique probability measure which is invariant under this notion of translation.

Having decided on the meaning of a uniform probability measure on the square, we are going to define a set of points as uniform if the uniform measure on the points approximates well the Lebesgue measure. In particular, let  $P \subset [0, 1]^2$  be a set of  $n$  points, and let  $S \subseteq [0, 1]^2$  be some measurable set. The probability that a uniformly random point in  $P$  lands in  $S$  is  $\frac{|P \cap S|}{n}$ . The discrepancy of  $P$  with respect to  $S$  is the difference between this probability and the area of  $S$ , denoted

$$D(P, S) = \frac{|P \cap S|}{|P|} - \lambda^2(S).$$

The idea here is that  $S$  is a “distinguishing set”: if we sample many points from  $P$  and they land in  $S$  with probability very different from  $\lambda^2(S)$ , then we know for sure that the points were not sampled uniformly from the square. We are usually interested in a the maximum discrepancy over a whole family of distinguishing sets. To this end, for a collection  $\mathcal{S}$  of measurable subsets of  $[0, 1]^2$ , we define the discrepancy of an  $n$ -point set  $P$  as

$$D(P, \mathcal{S}) = \sup_{S \in \mathcal{S}} |D(P, S)|.$$

If the discrepancy  $D(P, \mathcal{S})$  is small, then we cannot easily distinguish the uniform measure on  $P$  from the uniform measure on  $[0, 1]^2$  by sampling and computing how many points land in some set  $S$ . Once we fix a family  $\mathcal{S}$ , the most uniform set of  $n$  points in the square (with respect to  $\mathcal{S}$ ) is the one that minimizes the discrepancy, i.e. the one that achieves the discrepancy of  $\mathcal{S}$ , defined for every  $n$  as

$$D(n, \mathcal{S}) = \inf_{P \subset [0, 1]^2, |P|=n} D(P, \mathcal{S}).$$

The best studied family of distinguishers is the set of axis aligned rectangles  $\mathcal{R}_2$ , i.e. all sets of the form  $[x_1, y_1] \times [x_2, y_2]$  for  $x, y \in [0, 1]^2$ . We will focus on this family for purposes of illustration.

**Exercise 1.** Show that the grid  $P = \{(i/\sqrt{n}, j/\sqrt{n})\}$  where  $i = 0, \dots, \sqrt{n}-1$  and  $j = 0, \dots, \sqrt{n}-1$  (assume  $\sqrt{n}$  is an integer) has discrepancy  $D(P, \mathcal{R}_2) = \Theta(n^{-1/2})$ .

**Exercise 2.** Show that  $D(n, P) = \Omega(n^{-1})$ .

There are various constructions that give the bound  $D(n, \mathcal{R}_2) = O\left(\frac{\log n}{n}\right)$ , which is tight up to constants [4]. We give one construction below.

Note that there was nothing special about two dimensions in the discussion above. We can instead look for uniformly distributed sets of points in the unit  $d$ -dimensional cube  $[0, 1]^d$ . The unique uniform measure is the ( $d$ -dimensional) Lebesgue measure  $\lambda^d$ , i.e. the measure that associates a set  $S \subseteq [0, 1]^d$  with its  $d$ -dimensional volume. The definitions are analogous to the ones above: for an  $n$ -point set  $P \subset [0, 1]^d$ , a distinguishing set  $S \subseteq [0, 1]^d$ , and a family  $\mathcal{S}$  of distinguishing sets, we define

$$\begin{aligned} D(P, S) &= \frac{|P \cap S|}{|P|} - \lambda^d(S); \\ D(P, \mathcal{S}) &= \sup_{S \in \mathcal{S}} |D(P, S)|; \\ D(n, \mathcal{S}) &= \inf_{P \subset [0, 1]^d, |P|=n} D(P, \mathcal{S}). \end{aligned}$$

In the  $d$ -dimensional setting we will focus on the set of  $d$ -dimensional axis-aligned boxes  $\mathcal{R}_d$ , i.e. sets of the form  $[x_1, y_1] \times \dots \times [x_d, y_d]$  for  $x, y \in [0, 1]^d$ . Here, the best known lower bound on  $D(n, \mathcal{R}_d)$  is  $D(n, \mathcal{R}_d) = \Omega\left(\frac{(\log n)^{(d-1)/2 + \eta_d}}{n}\right)$  for some  $\eta_d$  that goes to 0 as  $d$  goes to infinity [2] (see also the excellent survey [1]). The best known upper bound is  $D(n, \mathcal{R}_d) = O\left(\frac{(\log n)^{d-1}}{n}\right)$ . Closing this significant gap is known as the ‘‘Great Open Problem’’ in geometric discrepancy theory.

## 2 Combinatorial Discrepancy

We now consider *combinatorial discrepancy*, which is an interesting measure in and of itself (and is also related to the usual continuous discrepancy, as we will see). Let  $\mathcal{U}$  be a set and let  $\mathcal{S} \subseteq 2^{\mathcal{U}}$  a family of subsets of  $\mathcal{U}$ ; together the pair  $(\mathcal{U}, \mathcal{S})$  is called a *set system*. Given a coloring  $\chi : \mathcal{U} \rightarrow \{-1, 1\}$  of the elements of  $\mathcal{U}$  with  $\pm 1$  we define

$$\text{disc}(\chi, \mathcal{S}) = \max_{S \in \mathcal{S}} |\chi(S)|$$

where  $\chi(S) = \sum_{u \in S} \chi(u)$ . Intuitively, this measures how balanced  $\chi$  is. A coloring  $\chi$  has small discrepancy if it colors about half the the elements of every set  $S \in \mathcal{S}$  with  $-1$  and about half with  $+1$ . The *discrepancy* of  $\mathcal{S}$  is then defined as

$$\text{disc}(\mathcal{S}) = \min_{\chi} \text{disc}(\chi, \mathcal{S})$$

where the minimum is taken over all colorings  $\chi : \mathcal{U} \rightarrow \{-1, 1\}$ .

Notice that if  $A \in \{0, 1\}^{\mathcal{S} \times \mathcal{U}}$  is the incidence matrix of  $\mathcal{S}$ , i.e. the matrix defined by

$$a_{S,u} = \begin{cases} 1 & u \in S \\ 0 & u \notin S \end{cases},$$

then  $\text{disc}(S) = \min_{x \in \{-1,1\}^U} \|Ax\|_\infty$ , where  $\|\cdot\|_\infty$  is the infinity norm defined by  $\|y\|_\infty = \max_i |y_i|$  with the maximum taken over the coordinates of  $y$ . We can now define the discrepancy  $\text{disc}(A) = \min_{x \in \{-1,1\}^n} \|Ax\|_\infty$  for any  $m \times n$  matrix  $A$ .

It will be important for us to consider a more robust version of discrepancy, known as *hereditary discrepancy*. The hereditary discrepancy is defined for an  $m \times n$  matrix  $A$  by  $\text{herdisc}(A) = \max_S \text{disc}(A_S)$  where the maximum is over all subsets  $S$  of  $[n] = \{1, \dots, n\}$ , and  $A_S$  is the submatrix of  $A$  consisting of the columns indexed by  $S$ . The hereditary  $\text{herdisc}(\mathcal{S})$  of a set system  $(\mathcal{S}, U)$  can be defined as  $\text{herdisc}(A)$ , where  $A$  is the incidence matrix of  $\mathcal{S}$  defined above, and equals the maximum discrepancy over restricted set systems  $\mathcal{S}|_W = \{S \cap W : S \in \mathcal{S}\}$ , with  $W$  ranging over subsets of the ground set  $U$ .

We have the following important lemma, due to Lovasz, Spencer, and Vesztergombi [3].

**Lemma 1.** *For any  $m \times n$  matrix  $A$ , and any  $w \in [0, 1]^n$ , there exists a  $x \in \{0, 1\}^n$  such that  $\|Ax - Aw\|_\infty \leq \text{herdisc}(A)$ .*

*Proof.* First an easy exercise.

**Exercise 3.** *Show that for any  $w \in \{0, \frac{1}{2}, 1\}^n$  there exists an  $x \in \{0, 1\}^n$  such that  $\|Ax - Aw\|_\infty \leq \frac{1}{2} \text{herdisc}(A)$ .*

To finish the proof of the lemma, it suffices to prove it for  $w$  such that  $w_i$  has a finite binary expansion for each  $i$ . We do so by induction. Let us assume that the lemma is proved for all  $w \in 2^{-k}\mathbb{Z}^n \cap [0, 1]^n$  for some  $k \geq 1$ . (Note that the case  $k = 1$  is the exercise above.) We will show that it then also holds for every  $w \in 2^{-k-1}\mathbb{Z}^n \cap [0, 1]^n$ . Fix such a  $w$ , and write it as  $w = w' + \frac{1}{2}w''$ , where  $w' \in \{0, \frac{1}{2}\}^n$  and  $w'' \in 2^{-k}\mathbb{Z}^n \cap [0, 1]^n$ . By the induction hypothesis, there exists an  $x'' \in \{0, 1\}^n$  such that  $\|Ax'' - Aw''\|_\infty \leq \text{herdisc}(A)$ . We have  $w' + \frac{1}{2}x'' \in \{0, \frac{1}{2}, 1\}$ , and, by the exercise above, there exists an  $x \in \{0, 1\}^n$  such that

$$\|Ax - A(w' + \frac{1}{2}x'')\|_\infty \leq \frac{1}{2} \text{herdisc}(A). \quad (1)$$

The inequality (1) and the triangle inequality then imply

$$\begin{aligned} \|Ax - Aw\|_\infty &= \|Ax - A(w' + \frac{1}{2}w'')\|_\infty \\ &\leq \|Ax - A(w' + \frac{1}{2}x'')\|_\infty + \frac{1}{2}\|Ax'' - Aw''\|_\infty \\ &\leq \text{herdisc}(A). \end{aligned}$$

This completes the proof of the lemma. □

We are now ready to relate combinatorial and geometric discrepancy.

**Theorem 2.** *Let  $\mathcal{S}$  be a class of Lebesgue measurable sets in  $[0, 1]^d$  such that  $[0, 1]^d \in \mathcal{S}$ , and let  $n \leq N$  positive integers. Then,*

$$D(n, \mathcal{S}) \leq \frac{2 \text{disc}(N, \mathcal{S})}{n} + D(N, \mathcal{S}).$$

Above  $\text{disc}(N, \mathcal{S}) = \max\{\text{disc}(\mathcal{S}|_P) : P \subset [0, 1]^d, |P| \leq N\}$ .

*Proof.* Take  $P$  to be a set of size  $N$  such that  $D(P, \mathcal{S}) = D(N, \mathcal{S})$ , and let  $A$  be the incidence matrix of  $\mathcal{S}|_P = \{S \cap P : S \in \mathcal{S}\}$ . Let  $w \in [0, 1]^P$  equal  $w_p = n/N$  for each  $p \in P$ . Then the coordinate corresponding to a set  $S \cap P$  of  $Aw$  equals  $(Aw)_{S \cap P} = \frac{n|P \cap S|}{N}$ . On the other hand, by Lemma 1, there exists an  $x \in \{0, 1\}^P$  such that

$$\|Ax - Aw\|_\infty \leq \text{herdisc}(\mathcal{S}|_P) \leq \text{disc}(N, \mathcal{S}), \quad (2)$$

where the last inequality is trivial from the definition of  $\text{disc}(N, \mathcal{S})$ . Define the point set  $Q \subseteq P$  to contain all points in  $P$  for which  $x_p = 1$ , so that for any  $S \in \mathcal{S}$  we have  $(Ax)_{S \cap P} = |S \cap Q|$ . Then by (2), for any  $S \in \mathcal{S}$  we have

$$\left| |Q \cap S| - \frac{n|P \cap S|}{N} \right| \leq \text{disc}(N, \mathcal{S}).$$

Together with the discrepancy bound on  $P$ , this means that

$$\left| \frac{|Q \cap S|}{n} - \lambda^d(S) \right| \leq \left| \frac{|Q \cap S|}{n} - \frac{|P \cap S|}{N} \right| + \left| \frac{|P \cap S|}{n} - \lambda^d(S) \right| \leq \frac{\text{disc}(N, \mathcal{S})}{n} + D(N, \mathcal{S}). \quad (3)$$

Moreover, because  $[0, 1]^d \in \mathcal{S}$ , we have that  $||Q \cap S| - n| \leq \text{disc}(N, \mathcal{S})$ . Let us construct  $Q'$  by arbitrarily adding or removing at most  $\text{disc}(N, \mathcal{S})$  points to  $Q$  so that  $|Q'| = n$ . Since  $||Q \cap S| - |Q' \cap S|| \leq \text{disc}(N, \mathcal{S})$ , together with (3) we get

$$\left| \frac{|Q' \cap S|}{n} - \lambda^d(S) \right| \leq \frac{2 \text{disc}(N, \mathcal{S})}{n} + D(N, \mathcal{S}).$$

Then,

$$D(n, \mathcal{S}) \leq D(Q', \mathcal{S}) \leq \frac{2 \text{disc}(N, \mathcal{S})}{n} + D(N, \mathcal{S}),$$

this completes the proof.  $\square$

For example, we can take  $N = n^2$  and using an  $n \times n$  grid we see that  $D(n^2, \mathcal{R}_2) \leq \frac{1}{n}$ . Later we will see that  $\text{disc}(n, \mathcal{R}_2) = O((\log n)^{1.5})$ . So Theorem 2 gives us that  $D(n, \mathcal{R}_2) = O((\log n)^{1.5}/n)$ , which is not quite the best bound we know, but comes quite close.

A more sophisticated way to use Theorem 2 is by repeated halving. Suppose that  $\text{disc}(2n, \mathcal{S}) \leq (2 - 2\delta) \text{disc}(n, \mathcal{S})$  and that  $D(n, \mathcal{S}) = o(1)$ . Then, by applying Theorem 2 with  $n$  and  $2n$ , and then  $2n$  and  $4n$ , and so on, we get

$$\begin{aligned} D(n, \mathcal{S}) &\leq \frac{2 \text{disc}(2n, \mathcal{S})}{n} + \frac{2 \text{disc}(4n, \mathcal{S})}{2n} + \dots + \frac{2 \text{disc}(N, \mathcal{S})}{N/2} + D(N, \mathcal{S}) \\ &\leq (1 + (1 - \delta) + (1 - \delta)^2 + \dots) \frac{2 \text{disc}(2n, \mathcal{S})}{n} + D(N, \mathcal{S}) \\ &\leq \frac{2 \text{disc}(2n, \mathcal{S})}{\delta n} + D(N, \mathcal{S}). \end{aligned}$$

Then we can take  $N$  big enough so that  $D(N, \mathcal{S}) \leq \frac{2 \text{disc}(2n, \mathcal{S})}{\delta n}$ , and we get

$$D(n, \mathcal{S}) \leq \frac{4 \text{disc}(2n, \mathcal{S})}{\delta n}.$$

In other words, under these mild assumptions,  $D(n, \mathcal{S}) = O(\text{disc}(n, \mathcal{S})/n)$ .

### 3 A Low Discrepancy Set for Rectangles

We first make two trivial but useful observations. Given two sets  $A, B \subseteq [0, 1]^2$ :

First, if  $A \cap B = \emptyset$  then

$$|D(P, A \cup B)| = |D(P, A) + D(P, B)| \leq |D(P, A)| + |D(P, B)|.$$

Secondly, if  $B \subseteq A$ , then

$$\begin{aligned} |D(P, A \setminus B)| &= |D(P, A) - D(P, B)| \\ &\leq |D(P, A)| + |D(P, B)|. \end{aligned}$$

It is often convenient to argue about the discrepancy of corners rather than rectangles. We define the set of  $d$ -dimensional corners as  $\mathcal{C}_d$  as the collection of sets of the form  $[0, x_d] \times \dots \times [0, x_d]$  for  $x \in [0, 1]^d$ . It turns out that the discrepancy with respect to rectangles and the discrepancy with respect to corners are equivalent up to constants.

**Exercise 4.** Show that for any  $d \geq 1$ , we have

$$D(P, \mathcal{C}_d) \leq D(P, \mathcal{R}_d) \leq 2^d D(P, \mathcal{C}_d). \quad (4)$$

From now on we will use discrepancy with respect to corners or rectangles interchangeably. The inequalities (4) imply that this does not affect the asymptotics of the discrepancy function.

**The bit reversal function:** We define the bit reversal function  $r(\cdot) : \mathbb{N} \rightarrow [0, 1]$  to be the function that takes an integer  $i$ , converts it into binary then reverses the bits and precedes them by 0.; to put it another way,  $r(i)$  flips the bits of the binary representation of  $i$  around the radix point. For instance  $1 = 1_2 \implies r(1) = 0.1_2 = 0.5$ ,  $2 = 10_2 \implies r(2) = 0.01_2 = 0.25$ , and so on. Formally, if  $a_0, \dots, a_{k-1} \in \{0, 1\}$  is the unique sequence such that  $i = \sum_{i=0}^{k-1} a_i 2^i$ , then

$$r(i) := \sum_{i=0}^{k-1} a_i 2^{-i-1}.$$

The *van der Corput Set* is the set of points defined as  $P = \{(\frac{i}{n}, r(i)) : i = 0 \dots n-1\}$ . For the rest of this subsection we will fix  $P$  to be this set.

**Theorem 3** (Van der Corput). For  $P$  the van der Corput set defined above,

$$D(P, \mathcal{R}_2) \leq 4 \cdot D(P, \mathcal{C}_2) = O(\log n).$$

We will sketch the proof of the theorem. First we prove:

**Claim 4.** Let  $I$  be an interval of the form  $I = [\frac{k}{2^q}, \frac{k+1}{2^q})$  where  $q$  is a positive integer and  $0 \leq k < 2^q - 1$ . Then for any  $x \in [0, 1]$ :

$$|D(P, [0, x] \times I)| \leq \frac{1}{n}$$

**Exercise 5.** Prove Claim 4.

Hint: It is enough to show that for any rectangle of the form  $R = \left[ \frac{\ell 2^q}{n}, \frac{(\ell+1)2^q}{n} \right) \times \left[ \frac{k}{2^q}, \frac{k+1}{2^q} \right)$ , for  $0 \leq k \leq 2^q - 1$  and  $0 \leq \ell \leq \frac{n}{2^q} - 1$ , we have  $|P \cap R| = 1$  and  $D(P, R) = 0$ .

*Proof of Theorem 3.* To prove the theorem, we use Claim 4 repeatedly. Let  $x, y \in [0, 1]^2$  be arbitrary. We need to show that  $|D(P, C_{xy})| = O(\log n)$ . First we choose the smallest integer  $q_0$  such that  $\frac{1}{2^{q_0}} \leq y$ ; by Claim 4, we have

$$|D(P, [0, x] \times [0, 2^{-q_0}])| \leq \frac{1}{n}.$$

Then we choose the smallest integer  $q_1 > q_0$  such that  $\frac{1}{2^{q_0}} + \frac{1}{2^{q_1}} \leq y$ ; again by Claim 4, we have

$$|D(P, [0, x] \times [0, (2^{q_1 - q_0} + 1)2^{-q_1}])| \leq \frac{1}{n}.$$

We continue in this manner for  $O(\log n)$  iterations. We illustrate the first iteration in Figure 1 below.

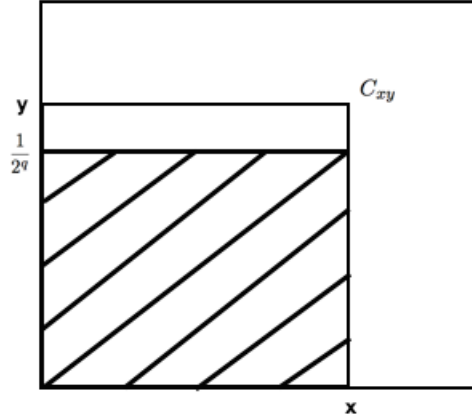


Figure 1: After 1 iteration

After  $O(\log n)$  iterations, the remaining rectangle must have area less than  $\frac{1}{n}$  and will contain at most one point of  $P$ , so it will have discrepancy  $\leq \frac{1}{n}$ . This implies the upper bound of  $O((\log n)/n)$  on the discrepancy of the van der Corput set.  $\square$

**Exercise 6.** Let us define  $r_2(i) = r(i)$ , as defined above, and, for a prime  $p$ , let

$$r_p(i) = \sum_{i=0}^{k-1} a_i p^{-i-1},$$

where  $a_0, \dots, a_{k-1}$  are the digits of  $i$  in base  $p$ , i.e. the unique sequence in  $\{0, \dots, p-1\}$  such that  $i = \sum_{i=0}^{k-1} a_i p^i$ . Let  $p_1 = 2, \dots, p_{d-1}$  be the first  $d-1$  primes. Show that the  $n$ -point set  $P = \{(\frac{i}{n}, r_2(i), \dots, r_{p_{d-1}}(i)) : i = 0 \dots n-1\}$  has discrepancy  $D(P, \mathcal{C}_d) = O\left(\frac{(\log n)^{d-1}}{n}\right)$ .

## References

- [1] Dmitriy Bilyk. On Roth's orthogonal function method in discrepancy theory. *Unif. Distrib. Theory*, 6(1):143–184, 2011.
- [2] Dmitriy Bilyk, Michael T. Lacey, and Armen Vagharshakyan. On the small ball inequality in all dimensions. *J. Funct. Anal.*, 254(9):2470–2502, 2008.
- [3] L. Lovász, J. Spencer, and K. Vesztergombi. Discrepancy of set-systems and matrices. *European J. Combin.*, 7(2):151–160, 1986.
- [4] Wolfgang Schmidt. Irregularities of distribution, vii. *Acta Arithmetica*, 1(21):45–50, 1972.