

# Learning Label Trees for Probabilistic Modelling of Implicit Feedback

Andriy Mnih & Yee Whye Teh  
Gatsby Computational Neuroscience Unit, University College London



## Summary

**An efficient probabilistic approach to collaborative filtering with implicit feedback, based on modelling the user's item selection process.**

- Tree-structured distributions over items for scalability.
- A principled and efficient algorithm for learning effective item trees from data.
- A fix for the standard evaluation protocol for implicit feedback models, addressing its unrealistic assumptions.

## Introduction

Collaborative filtering is the method of choice for inferring complex user preference patterns from large collections of feedback data.

- **Explicit feedback:** ratings given by users to items
  - Received a lot of attention: several very effective methods
  - Ratings can be scarce or expensive to collect
- **Implicit feedback:** user purchase or click history
  - Easier to collect than explicit feedback: produced by common user actions
  - The existing methods are not fully probabilistic

## Modelling item selection

Our approach is to model the item selection process:

- Treat chosen items as samples from a user-specific distribution.
- The probability of an item under the user's distribution  $P(i|u)$  quantifies the degree of the user's interest.
- User and item properties are captured by latent factor vectors:
  - $U_u$  for user  $u$ ,  $V_i$  for item  $i$ .
- The probability of user  $u$  choosing item  $i$  is given by

$$P(i|u) = \frac{\exp(U_u^\top V_i + b_i)}{\sum_k \exp(U_u^\top V_k + b_k)}$$

- Computing the probability of an item takes too long, as it requires considering all available items.
- **Idea: Associate items with the leaves of a binary tree and exploit its structure to speed up normalization exponentially.**

## Tree-structured item space

- One-to-one correspondence between root-to-leaf paths and items.
- Choosing an item now involves a sequence of  $\Theta(\log_K N)$   $K$ -way decisions, instead of a single  $N$ -way decision.
- Making the  $K$ -way decisions probabilistic induces a distribution over items.

## Hierarchical item selection model (HIS)

- For user  $u$ , the probability of moving from node  $n_j$  to node  $n$  during a root-to-leaf tree traversal is given by

$$P(n|n_j, u) = \frac{\exp(U_u^\top Q_n + b_n)}{\sum_{m \in C(n_j)} \exp(U_u^\top Q_m + b_m)},$$

if  $n$  is a child of  $n_j$  and 0 otherwise.

–  $C(n_j)$  is the set of children of node  $n_j$ .

–  $Q_n$  and  $b_n$  are the factor vector and the bias of node  $n$ .

- The probability of selecting item  $i$  is the probability of following the path  $n_0^i, \dots, n_{l_i}^i$  that starts at the root and stops at the leaf containing  $i$ :

$$P(i|u) = \prod_{j=1}^{l_i} P(n_j^i | n_{j-1}^i, u).$$

## Learning item trees

- We would like to learn the tree structure jointly with the model parameters, but maximizing the log-likelihood w.r.t. the tree structure is intractable.
- **We learn the tree greedily, one level at a time.**
  - For simplicity, we assume that user factor vectors are known and fixed.
- **Top-down hierarchical model-based clustering of items.**
  - Start with all items assigned to the root node.
  - Recursively, partition the set of items at each node among its  $K$  children.
  - Update the node assignment for one item at a time as to approximately maximize the log-likelihood.
- **Difficulty:** The effect of moving an item between nodes at level  $l$  on the log-likelihood depends on the future nodes  $n_{l+1}^i, \dots, n_{l_i}^i$  of the item paths.
  - We approximate the user-dependent tree-structured distribution over items below a node at the current depth by a user-independent flat distribution.
  - This produces a lower-bound on the achievable likelihood for the complete tree-structured model.

## Learning a tree level

Suppose we have learned the first  $l - 1$  nodes of each item path and would like to learn the  $l^{\text{th}}$  node. The contribution of item  $i$  to the log-likelihood of the still-to-be-learned levels of the tree is

$$L_i^l = \sum_{u \in U_i} (\log P(n_l^i | n_{l-1}^i, u) + \log P(i | n_l^i, u)),$$

where  $U_i$  is the set of users who rated item  $i$  in the training set and  $P(i | n_l^i, u) = \prod_{j=l+1}^{l_i} P(n_j^i | n_{j-1}^i, u)$ . Adding up the contributions from all items gives

$$L^l = \sum_i \left( \sum_{u \in U_i} \log P(n_l^i | n_{l-1}^i, u) + \sum_{u \in U_i} \log P(i | n_l^i, u) \right).$$

Approximating the tree-structured user-dependent  $P(k | n_l^k, u)$  with a flat user-independent distribution  $P(k | n_l^k)$  gives

$$\tilde{L}^l = \sum_i \left( \sum_{u \in U_i} \log P(n_l^i | n_{l-1}^i, u) + |U_i| \log P(i | n_l^i) \right).$$

$\tilde{L}^l$  can be maximized w.r.t.  $n_l^i$  in  $O(K)$  time since the user factor vectors are fixed and the model is log-linear in them.

## Algorithm for learning a tree level

- Initialize  $\{n_l^i\}$  randomly
- Repeat until convergence:
  - Pick a user/item pair from the training set
  - Set  $n_l^i$  and  $P(i | n_l^k)$  to the values that jointly maximize  $\tilde{L}^l$
  - Update  $Q_{n_l^i}$  using an online estimate of the gradient of  $\tilde{L}^l$

## Training procedure

1. Train a model based on a random tree and extract user factor vectors.
2. Learn a tree from the (fixed) user factor vectors.
3. Train a model based on the learned tree, updating both user and item factor vectors.

Note: Each of the three stages is online as model parameters are updated after each user/item pair. However, the set of items has to be fixed in advance.

## Evaluation protocol

Implicit feedback models are evaluated using information retrieval metrics.

- Need to know which items are relevant and which are not.
- Typically items that are not selected by the user are assumed to be irrelevant.
- Problematic, as some of those items are actually relevant.

**Our approach: use a small quantity of explicit feedback to identify the truly not relevant items.**

## Results

- MovieLens 10M dataset
  - Ratings on a scale from 0 to 5
  - 69878 users and 10677 movies
  - Keep user/item pairs with ratings 4 and higher
- We compare to Binary Matrix Factorization (BMF) and Bayesian Personalized Ranking (BPR).
- Not relevant  $\equiv$  rated 2 or lower

Model	PPL	MAP	P@1	P@10	R@1	R@10
BMF	–	70.80	75.66	49.77	20.94	77.21
BPR	865	<b>72.75</b>	75.75	50.63	21.50	<b>78.39</b>
HIS (Random)	921	70.68	74.65	49.91	20.66	77.31
HIS (LearnRI)	822	72.50	76.64	50.64	21.51	78.22
HIS (LearnCI)	<b>820</b>	72.61	<b>76.68</b>	<b>50.69</b>	<b>21.54</b>	78.27

- Not relevant  $\equiv$  unrated

Model	MAP	P@1	P@10	R@1	R@10
BMF	<b>16.13</b>	<b>22.10</b>	<b>12.94</b>	<b>4.66</b>	<b>23.55</b>
BPR	12.73	14.27	9.89	3.06	18.86

## Conclusion and future work

- We introduce a new approach to modelling implicit feedback using tree-structured distributions over items, along with a principled algorithm for learning the item trees.
- Competitive with the best existing methods.
- Future work:
  - A fully online version of the tree-learning algorithm
  - Multiple leaves per item for greater flexibility
  - Application to classification with many classes

Support: Gatsby Charitable Foundation; European Community's Seventh Framework Programme (FP7/2007-2013) grant agreement No. 270327.