

On the Topologies Formed by Selfish Peers

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Social Networks Seminar Fall 2007

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Introduction

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 - Collaboration of peers to build scalable decentralized systems
 - e.g. BitTorrent for file distribution

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- Problem: many peers are *selfish*
 - Minimize own cost
- Use a *game-theoretic* approach to study the effect of selfish peers on the topology of a P2P system
 - Price of anarchy: $\Theta(\min(\alpha, n))$
 - Topologies may not converge to a stable state (Nash equilibrium)

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- Network Formation Game
 - Strategy space of π_i : $S_i = 2^{V \setminus \{\pi_i\}}$
 - π_i maintains or establishes a link to π_j if $\pi_j \in s_i$, where $s_i \in S_i$
 - $s = (s_0, \dots, s_{n-1}) \in S_0 \times \dots \times S_{n-1}$ yields a directed graph $G[s] = (V, \bigcup_{i=0}^{n-1} (\{\pi_i\} \times s_i))$ describing the P2P topology

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In plain English, each peer decides whether to establish a direct link to each of its other peers

⇒ a directed graph with peers as nodes and links as edges

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- Each peer has a cost function

$$c_i(s) = \alpha \cdot |s_i| + \sum_{i \neq j} stretch_{G[s]}(\pi_i, \pi_j)$$

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- α is a parameter measuring the relative importance between node degree and stretch in the cost function

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- Price of anarchy =

$$\frac{\text{social cost of worst NE}}{\text{social cost of optimal topology}}$$

Upper Bound

Theorem 4.1 (Upper bound)

For any metric space \mathcal{M} , the Price of Anarchy is $O(\min(\alpha, n))$

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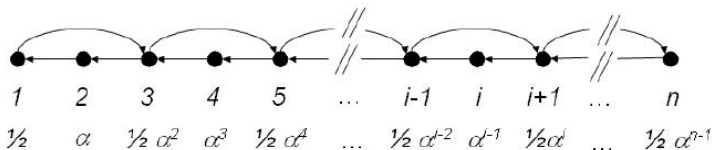


Figure 1: Example topology G where the Price of Anarchy is $\Theta(\min(\alpha, n))$ for $3.4 \leq \alpha$.

Lower Bound

Lemma 4.2

The topology G shown in Figure 1 forms a Nash equilibrium for $\alpha \geq 3.4$

Lemma 4.3

The social cost $C(G)$ of the topology G shown in Figure 1 is $C(G) \in \Theta(\alpha n^2)$

Theorem 4.4

The Price of Anarchy of the peer topology G shown in Figure 1 is $\Theta(\min(\alpha, n))$

Main Theorem

Theorem 5.1

Regardless of the magnitude of α , there are metric spaces \mathcal{M} , for which there exists no pure Nash equilibrium, i.e. certain P2P networks cannot converge to a stable state. This is the case even if \mathcal{M} is a 2-dimensional Euclidean space.

Illustration

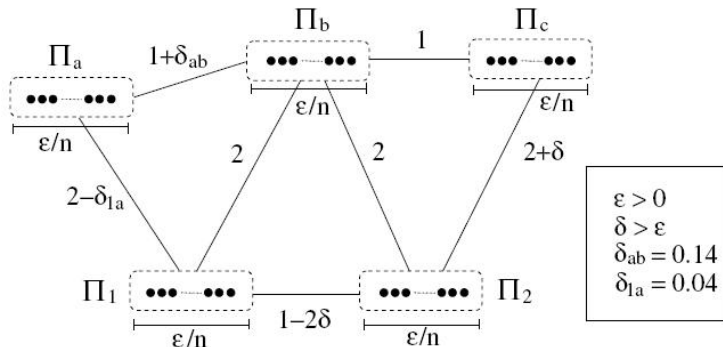


Figure 2: Instance I_k has no pure Nash equilibrium when $\alpha = 0.6k$, where $k = n/5$. The number of peers in each cluster is k .

Complexity

Theorem 6.1

Regardless of the magnitude of α , determining whether a given P2P network represented by a metric space \mathcal{M} has a pure Nash equilibrium (and can therefore stabilize) is NP-hard.

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 - Directed instead of undirected links
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- Game-theoretic model of a P2P system
- Bounds of Price of Anarchy
- (Non-)Existence of Nash equilibria

Implications of Selfish Neighbor Selection in Overlay Networks

N. Laoutaris, G. Smaragdakis, A. Bestavros and J. Byers

Social Networks Seminar

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Motivation

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 - ▶ PRACTICAL INTEREST?
- ▶ Players do not play in a socially optimal way: selfish

Scope and Contributions

- ▶ More practical model: for P2P and overlay routing application
 - ▶ Bounded Degree
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- ▶ Wiring Strategy: “Best Response”
- ▶ Experimental Results

Definitions

- ▶ Set of nodes: $V = \{v_1, v_2, \dots, v_n\}$
- ▶ Edge $e = \{v_i, v_j\}$: *Directed and Weighted*
- ▶ Preference vector: $p_i = \{p_{i1}, p_{i2}, \dots, p_{ii-1}, p_{ii+1}, p_{in}\}$
- ▶ Wiring of v_i : $s_i = \{v_{i_1}, v_{i_2}, \dots, v_{i_{k_i}}\}$
- ▶ Global Wiring: $S = \{s_1, s_2, \dots, s_n\}$
- ▶ Cost between v_i, v_j over S : $d_S(v_i, v_j)$
- ▶ Cost of v_i under S : $C_i(S) = \sum_{j=1, j \neq i}^n p_{ij} \times d_S(v_i, v_j)$

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(Nash Equilibrium of the SNS game)

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- ▶ For a node v_i
 - ▶ $Y_l \in \{0, 1\}^{n-1}$: if v_i wires to v_l
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- ▶ BR for v_i under S_{-i} , an *Integer Linear Program*

- ▶ Minimize:

$$C_i(S_{-i}, X) = \sum_{j=1, j \neq i}^n p_{ij} \sum_{l=1, l \neq i}^n X_{lj} \times (d_{il} + d_{S_{-i}}(v_l, v_j))$$

- ▶ Subject to:

$$\sum_{l=1, l \neq i}^n X_{lj} = 1, \forall j \neq i \text{ and } \sum_{l=1, l \neq i}^n Y_l = k_i \text{ and } X_{ij} \leq Y_l, \forall l, j \neq i$$

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To Find Stable Wirings

► Iterative Best Response

At the m -th iteration, for all nodes, do

1. v_i computes its best response $s_i^{(m)}$ to $S_{-i}^{(m,i-1)}$
2. $S^{(m,i)} = S_{-i}^{(m,i-1)} + \{s_i^{(m)}\}$
3. Do this until iteration \mathcal{M} : $s_i^{(\mathcal{M})} = s_i^{(\mathcal{M}-1)}$, $\forall v_i \in V$

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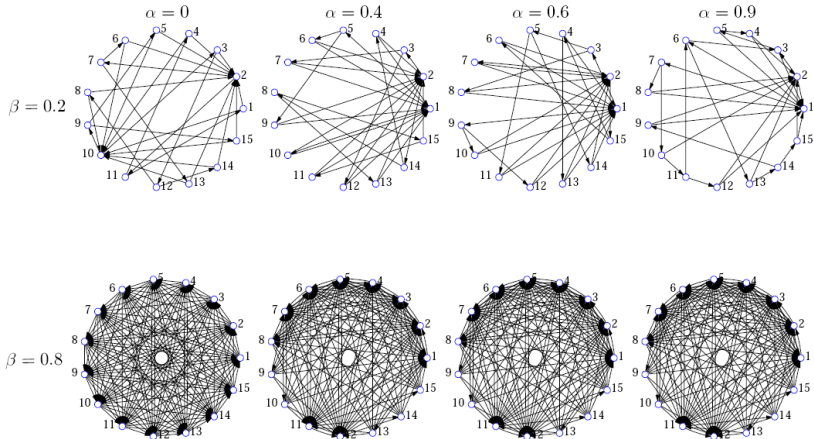
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 - ▶ $\beta \in [0, 1]$: link density
 - ▶ Out-degree of each node: $k = \lceil n^\beta \rceil$

Characterization of Stable Wirings

Note: "Hubs"



Performance of Newcomers: the cost

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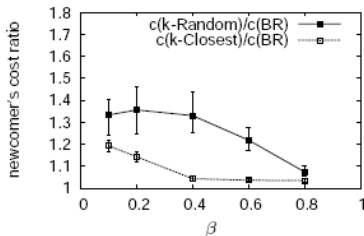
- ▶ Newcomers using different strategies entering graphs constructed by different strategies.

Performance of Newcomers

Newcomers to a k -random graph

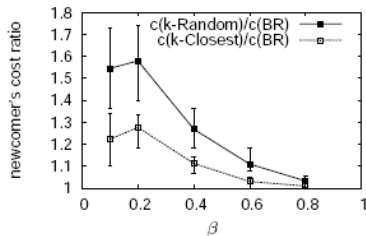
BRITE

on a k -Random graph with n nodes



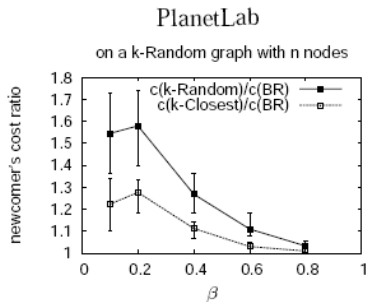
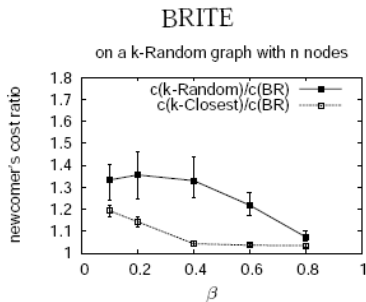
PlanetLab

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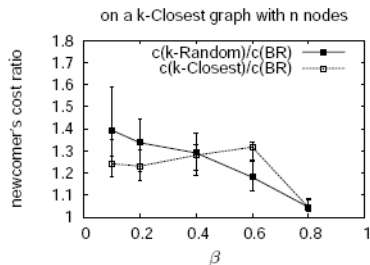
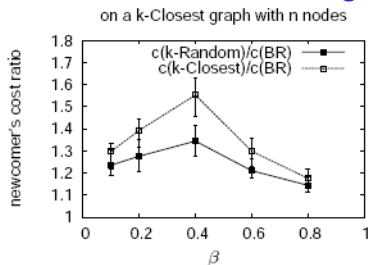
Newcomers to a k -random graph



It pays to "cheat".

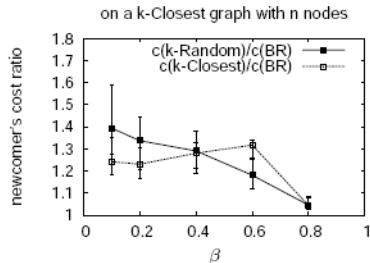
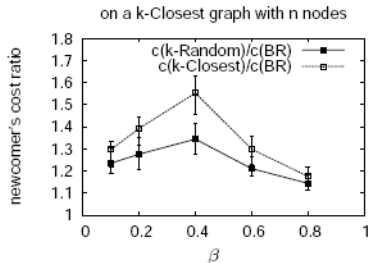
Performance of Newcomers

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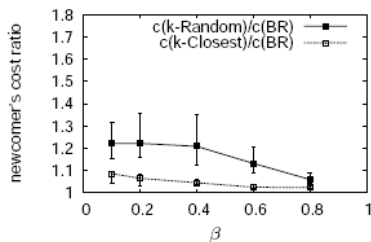


It does NOT pay to cheat, it may even hurt!

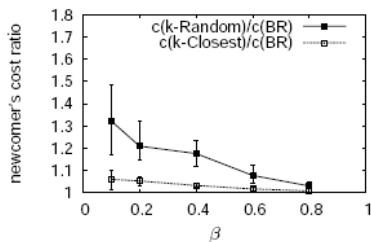
Performance of Newcomers

Newcomers to a BR graph

on a Best Response graph with n nodes



on a Best Response graph with n nodes



Knowledge Gained

- ▶ For prior arrivals: it is good to be selfish.
- ▶ For newcomers: should be careful.

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 - ▶ **A**: Trade-off between degree and distance
 - ▶ **B**: The optimization under certain restrictions

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 - ▶ **B**: Sometimes it is good to be selfish.

Conclusion on Papers **A** and **B**

- ▶ Extension

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- ▶ Extension
 - ▶ The joining (or leaving) of players.

Conclusion on Papers A and B

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 - ▶ The joining (or leaving) of players.
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