## The Cook-Levin Theorem

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**Theorem 8.7 (Cook '71, Levin '73)** The satisfiability problem for propositional formulas, SAT, is **NP**-complete.

PROOF. It is clear that SAT is in **NP** (the certificate is a truth assignment, which is short, and the verifier checks that the truth assignment satisfies the formula, which can be done in polynomial time). The more interesting part is the proof that SAT in **NP**-hard. Take any decision problem  $A \subseteq \Sigma^*$  in **NP**, and let  $M_A = (Q, \Sigma, \Gamma, \delta, q_0, h_A, h_R)$  be a nondeterministic Turing machine that decides A in polynomial time, say p(n), where n is the length of the input x. Without loss of generality we can assume that  $p(n) \ge n$ ; we can do this by requiring  $M_A$  to read its input before doing anything else. This adds at most n steps to the length of the computation of  $M_A$  on x, and therefore does not affect the fact that  $M_A$  runs in polynomial time.

Given any  $x \in \Sigma^*$  we show how to construct a propositional formula  $F_x$  that is satisfiable if and only if  $x \in A$ ; that is, if and only if  $M_A$  on input x has an accepting computation path  $C_0 \vdash C_1 \vdash \cdots \vdash C_\ell$ , where  $\ell \leq p(|x|)$ . The length of  $F_x$  will be polynomial in |x|, and it will be obvious that it can be constructed from x in polynomial time in |x|. Fix any  $x \in \Sigma^*$  and let n = |x|.

The propositional variables involved in  $F_x$  describe the state of affairs in the computation of  $M_A$  on input x at each "time" t (i.e., after t steps),  $0 \le t \le p(n)$ . (If  $\ell < p(n)$  we will imagine that  $M_A$  keeps going until time p(n) without changing its state, head position, or tape contents.) The variables are listed below, along with their intended meaning.

- $S_t^q$ , for  $0 \le t \le p(n)$  and  $q \in Q$ : At time t,  $M_A$  is in state q.
- $H_t^i$ , for  $0 \le t \le p(n)$  and  $1 \le i \le p(n) + 1$ : At time t, the head of  $M_A$  is on cell i. Note that in p(n) steps the rightmost cell that  $M_A$  can reach is p(n) + 1.
- $T_t^{ia}$ , for  $0 \le t \le p(n)$ ,  $1 \le i \le p(n)$ , and  $a \in \Gamma$ : At time t, the cell i of  $M_A$ 's tape contains symbol a. (Note that all cells to the right of cell p(n) can only contain blanks.)

Thus our formula will have  $O(p(n)) + O(p^2(n)) + O(p^2(n)) = O(p^2(n))$  variables, i.e., a polynomial number of them. Note that the number of states |Q| and the number of symbols  $|\Gamma|$  are constants: these depend on  $M_A$ , not on the input x.

The formula  $F_x$  is the conjunction of four subformulas, each expressing a requirement for the computation path of  $M_A$  on input x to be valid and accepting:

(1) Intuitively the subformula  $F_x^1$  states that, at each time t, the variables describe a coherent state of affairs:  $M_A$  is in at most one state, its head is in at most one place, and each tape cell contains at most one symbol. (It will follow from this and other subformulas that  $M_A$  is actually in exactly one state, the head in exactly one place, and each cell has exactly one symbol.) This is expressed as follows:

$$F_x^1 = \bigwedge_{0 \le t \le p(n)} \bigg( \bigg( \bigwedge_{p \ne q \in Q} \underbrace{(\neg S_t^p \lor \neg S_t^q)}_{\text{not in two states}} \bigg) \land \bigg( \bigwedge_{1 \le i < j \le p(n)+1} \underbrace{(\neg H_t^i \lor \neg H_t^j)}_{\text{not in two places}} \bigg) \land \bigg( \bigwedge_{1 \le i \le p(n)} \bigwedge_{a \ne b \in \Gamma} \underbrace{(\neg T_t^{ia} \lor \neg T_t^{ib})}_{\text{not wo symbols}} \bigg) \bigg).$$

(2) Intuitively the subformula  $F_x^2$  states that the computation of  $M_A$  on x starts well: At time 0,  $M_A$  is in its initial state  $q_0$ , its head is on cell 1, and the tape contains the input x in the first n cells and blanks in cells n + 1..p(n). This is expressed as follows: Let  $x = a_1 a_2 ... a_n$ , where each  $a_i \in \Sigma$ .

$$F_x^2 = S_0^{q_0} \wedge \underbrace{\left(\bigwedge_{1 \le i \le n} T_0^{ia_i}\right)}_{x \text{ in first } n \text{ cells}} \wedge \underbrace{\left(\bigwedge_{n+1 \le i \le p(n)} T_0^{i \sqcup}\right)}_{\text{blanks in rest}}.$$

(3) Intuitively the subformula  $F_x^3$  states that the computation of  $M_A$  on x ends well: At time p(n),  $M_A$  is in its accept state  $h_A$ . This is expressed as follows:

$$F_x^3 = S_{p(n)}^{h_A}$$

- (4) Finally, the subformula  $F_x^4$  is the conjunction of three other formulas,  $F_x^{4a}$ ,  $F_x^{4b}$ , and  $F_x^{4c}$ , which intuitively state that the move from time t to time t + 1 is consistent with the definition of  $M_A$ :
  - $F_x^{4a}$  states that only the symbol that is under the tape head at time t can change.
  - $F_x^{4b}$  states that as long as the current state of the TM is not a halting state (accept or reject), in the next step the state of affairs changes according to the (nondeterministic) transition function of  $M_A$ .
  - $F_x^{4c}$  states that after reaching a halting state, things don't change.

These are expressed as follows:

$$F_x^{4a} = \bigwedge_{0 \le t < p(n)} \bigwedge_{1 \le i \le p(n)} \bigwedge_{a \in \Gamma} \left( \neg T_t^{ia} \lor T_{t+1}^{ia} \lor H_t^i \right).$$

$$F_x^{4b} = \bigwedge_{0 \le t < p(n)} \bigwedge_{q \in Q - \{h_A, h_R\}} \bigwedge_{1 \le i \le p(n)} \bigwedge_{a \in \Gamma} \left( \left( \neg S_t^q \lor \neg H_t^i \lor \neg T_t^{ia} \right) \lor \left( \bigvee_{(p, b, D) \in \delta(q, a)} \left( S_{t+1}^p \land H_{t+1}^{i+d} \land T_{t+1}^{ib} \right) \right) \right).$$

where

$$d = \begin{cases} 1, & \text{if } D = R \\ -1, & \text{if } D = L \text{ and } i \neq 1 \\ 0, & \text{otherwise} \end{cases}$$

$$F_x^{4c} = \bigwedge_{0 \le t < p(n)} \bigwedge_{q \in \{h_A, h_R\}} \bigwedge_{1 \le i \le p(n)} \bigwedge_{a \in \Gamma} \left( \left( \neg S_t^q \lor \neg H_t^i \lor \neg T_t^{ia} \right) \lor \left( \left( S_{t+1}^q \land H_{t+1}^i \land T_{t+1}^{ia} \right) \right) \right).$$

So, the overall forula  $F_x$  is

$$F_x = F_x^1 \wedge F_x^2 \wedge F_x^3 \wedge (F_x^{4a} \wedge F_x^{4b} \wedge F_x^{4c}).$$

Given the semantics of each subformula,  $F_x$  asserts that  $M_A$  on input x has an accepting computation path. In other words,

 $F_x$  is satisfiable if and only if  $x \in A$ . (\*)

IF: If  $x \in A$ , there is an accepting computation path  $C_0 \vdash C_1 \vdash \ldots \vdash C_\ell$  of  $M_A$  on x. From this sequence of configurations we can define truth values for all the variables based on their intended meaning:  $S_t^q$  is true if  $C_t$  contains the state q and false otherwise,  $H_t^i$  is true if in  $C_t$  the head is on cell i of the tape and false otherwise, and  $T_t^{ia}$  is true of in  $C_t$  cell *i* of the tape contains symbol *a* and false otherwise. If  $\ell < p(n)$  we also define the truth values of the variables corresponding to times  $t, \ell < t \leq p(n)$ , to be equal to their values at time  $\ell$ . Because  $C_0 \vdash C_1 \vdash \cdots \vdash C_\ell$  is an accepting computation path of  $M_A$  on x, this truth assignment satisfies all subformulas  $F_x^1, F_x^2, F_x^3, F_x^{4a}, F_x^{4b}$ , and  $F_x^{4c}$ , and therefore it satisfies their conjunction  $F_x$ ; therefore,  $F_x$  is indeed satisfiable.

ONLY IF: Suppose  $F_x$  is satisfiable, and let  $\tau$  be a truth assignment to the variables that satisfies  $F_x$ . From this truth assignment we can define a sequence  $C_0, C_1, \ldots, C_{p(n)}$  so that

- $C_0$  is the initial configuration of  $M_A$  on x (this is because  $\tau$  satisfies  $F_x^2$ );
- for each  $t, 0 \le t < p(n), C_t$  is a legal configuration of  $M_A$ ; and either the state of  $M_A$  in  $C_t$  is not the accept or reject state and  $C_t \vdash C_{t+1}$ , or the state in  $C_t$  is the accept or reject state and  $C_t \models C_{t+1}$  (this is because  $\tau$  satisfies  $F_x^1, F_x^{4a}, F_x^{4b}$ , and  $F_x^{4c}$ ); and
- $C_p(n)$  is a configuration in the accept state (this is because  $\tau$  satisfies  $F_x^3$ .

Therefore for some  $\ell$ ,  $0 \leq \ell \leq p(n)$ ,  $C_0 \vdash C_1 \vdash \ldots \vdash C_\ell$  is an accepting computation path of  $M_A$  on x, which means that  $x \in A$ . This completes the proof of (\*).

Now let us calculate the length of  $F_x$ , measured as the number of variable occurrences. Recalling that |Q| and  $|\Gamma|$  are constants we see that the lengths of  $F_x^1$ ,  $F_x^2$ ,  $F_x^3$ ,  $F_x^{4a}$ ,  $F_x^{4b}$ , and  $F_x^{4c}$  are, respectively,  $O(p^3(n))$ , O(p(n)), O(1),  $O(p^2(n))$ ,  $O(p^2(n))$ , and  $O(p^2(n))$ . (For  $F_x^{4b}$  note that the maximum number of choices due to the nondeterminism of  $M_A$  is  $(|Q| - 2) \cdot |\Gamma|$ , which is constant.) Therefore the size of  $F_x$  is polynomial in n (the length of the input x), and obviously can be constructed from x in polynomial time.

So there is a polynomial time mapping reduction from any decision problem in NP to SAT.  $\Box$