CSC 411: Lecture 07: Multiclass Classification

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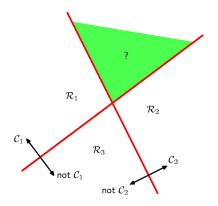
Today

Multi-class classification with:

- Least-squares regression
- Logistic Regression
- K-NN
- Decision trees

Discriminant Functions for K > 2 classes

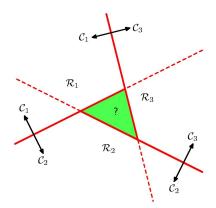
- Use K-1 classifiers, each solving a two class problem of separating point in a class C_k from points not in the class.
- Known as 1 vs all or 1 vs the rest classifier



• PROBLEM: More than one good answer!

Discriminant Functions for K > 2 classes

- Introduce K(K-1)/2 two-way classifiers, one for each possible pair of classes
- Each point is classified according to majority vote amongst the disc. func.
- Known as the 1 vs 1 classifier



• PROBLEM: Two-way preferences need not be transitive

K-Class Discriminant

ullet We can avoid these problems by considering a single K-class discriminant comprising K functions of the form

$$y_k(\mathbf{x}) = \mathbf{w}_k^T \mathbf{x} + w_{k,0}$$

and then assigning a point x to class C_k if

$$\forall j \neq k$$
 $y_k(\mathbf{x}) > y_j(\mathbf{x})$

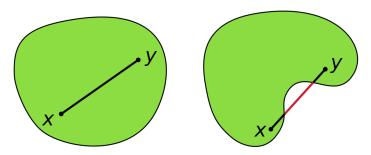
- Note that \mathbf{w}_k^T is now a vector, not the k-th coordinate
- The decision boundary between class C_j and class C_k is given by $y_j(\mathbf{x}) = y_k(\mathbf{x})$, and thus it's a (D-1) dimensional hyperplane defined as

$$(\mathbf{w}_k - \mathbf{w}_j)^T \mathbf{x} + (w_{k0} - w_{j0}) = 0$$

- What about the binary case? Is this different?
- What is the shape of the overall decision boundary?

K-Class Discriminant

- The decision regions of such a discriminant are always singly connected and convex
- In Euclidean space, an object is convex if for every pair of points within the object, every point on the straight line segment that joins the pair of points is also within the object

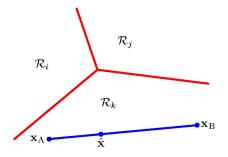


Which object is convex?

K-Class Discriminant

- The decision regions of such a discriminant are always singly connected and convex
- Consider 2 points \mathbf{x}_A and \mathbf{x}_B that lie inside decision region R_k
- Any convex combination $\hat{\mathbf{x}}$ of those points also will be in R_k

$$\hat{\mathbf{x}} = \lambda \mathbf{x}_A + (1 - \lambda) \mathbf{x}_B$$



Proof

• A convex combination point, i.e., $\lambda \in [0,1]$

$$\hat{\mathbf{x}} = \lambda \mathbf{x}_A + (1 - \lambda)\mathbf{x}_B$$

• From the linearity of the classifier y(x)

$$y_k(\hat{\mathbf{x}}) = \lambda y_k(\mathbf{x}_A) + (1 - \lambda)y_k(\mathbf{x}_B)$$

- Since \mathbf{x}_A and \mathbf{x}_B are in R_k , it follows that $y_k(\mathbf{x}_A) > y_j(\mathbf{x}_A)$, $y_k(\mathbf{x}_B) > y_j(\mathbf{x}_B)$, $\forall j \neq k$
- Since λ and 1λ are positive, then $\hat{\mathbf{x}}$ is inside R_k
- Thus R_k is singly connected and convex

Multi-class classification via the "softmax"

 Associate a set of weights with each class, then use a normalized exponential output

$$p(C_k|\mathbf{x}) = y_k(\mathbf{x}) = \frac{\exp(z_k)}{\sum_j \exp(z_j)}$$

where the activations are given by

$$z_k = \mathbf{w}_k^T \mathbf{x}$$

- For the target vector, if there are K classes we often use a 1-of-K encoding, i.e., a vector of K target values containing a single 1 for the correct class and zeros elsewhere
- ullet Let $oldsymbol{\mathsf{T}} \in \{0,1\}^{N imes K}$ for N training examples and K classes

Multi-class Logistic Regression

The likelihood

with

and

$$p(\mathbf{T}|\mathbf{w}_1, \dots, \mathbf{w}_k) = \prod_{n=1}^N \prod_{k=1}^K p(C_k|\mathbf{x}^{(n)})^{t_k^{(n)}} = \prod_{n=1}^N \prod_{k=1}^K y_k^{(n)} (\mathbf{x}^{(n)})^{t_k^{(n)}}$$
$$p(C_k|\mathbf{x}) = y_k(\mathbf{x}) = \frac{\exp(z_k)}{\sum_j \exp(z_j)}$$
$$z_k = \mathbf{w}_k^T \mathbf{x} + w_{k0}$$

- What assumptions have I used to derive the likelihood?
- Derive the loss by computing the negative log-likelihood

$$E(\mathbf{w}_1, \dots, \mathbf{w}_K) = -\log p(\mathbf{T}|\mathbf{w}_1, \dots, \mathbf{w}_K) = -\sum_{n=1}^{N} \sum_{k=1}^{K} t_k^{(n)} \log[y_k^{(n)}(\mathbf{x}^{(n)})]$$

- This is known as the cross-entropy error for multiclass classification
- How do we obtain the weights?

Training Multi-class Logistic Regression

$$E(\mathbf{w}_1,\cdots,\mathbf{w}_K) = -\log p(\mathbf{T}|\mathbf{w}_1,\cdots,\mathbf{w}_K) = -\sum_{n=1}^N \sum_{k=1}^K t_k^{(n)} \log[y_k^{(n)}(\mathbf{x}^{(n)})]$$

• Do gradient descent, where the derivatives are

$$\frac{\partial y_j^{(n)}}{\partial z_k^{(n)}} = \delta(k, j) y_j^{(n)} - y_j^{(n)} y_k^{(n)}$$

and

$$\frac{\partial E}{\partial z_k^{(n)}} = \sum_{j=1}^K \frac{\partial E}{\partial y_j^{(n)}} \cdot \frac{\partial y_j^{(n)}}{\partial z_k^{(n)}} = y_k^{(n)} - t_k^{(n)}$$

$$\frac{\partial E}{\partial w_{k,j}} = \sum_{n=1}^N \sum_{j=1}^K \frac{\partial E}{\partial y_j^{(n)}} \cdot \frac{\partial y_j^{(n)}}{\partial z_k^{(n)}} \cdot \frac{\partial z_k^{(n)}}{\partial w_{k,j}} = \sum_{n=1}^N (y_k^{(n)} - t_k^{(n)}) \cdot x_j^{(n)}$$

• The derivative is the error times the input

Softmax for 2 Classes

Let's write the probability of one of the classes

$$p(C_1|\mathbf{x}) = y_1(\mathbf{x}) = \frac{\exp(z_1)}{\sum_j \exp(z_j)} = \frac{\exp(z_1)}{\exp(z_1) + \exp(z_2)}$$

• I can equivalently write this as

$$p(C_1|\mathbf{x}) = y_1(\mathbf{x}) = \frac{\exp(z_1)}{\exp(z_1) + \exp(z_2)} = \frac{1}{1 + \exp(-(z_1 - z_2))}$$

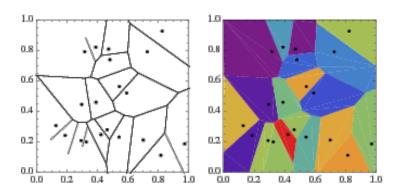
- So the logistic is just a special case that avoids using redundant parameters
- Rather than having two separate set of weights for the two classes, combine into one

$$z' = z_1 - z_2 = \mathbf{w}_1^T \mathbf{x} - \mathbf{w}_2^T \mathbf{x} = \mathbf{w}^T \mathbf{x}$$

• The over-parameterization of the softmax is because the probabilities must add to 1.

Multi-class K-NN

• Can directly handle multi class problems



Multi-class Decision Trees

- Can directly handle multi class problems
- How is this decision tree constructed?

