CSC321 Lecture 5 Learning in a Single Neuron

Roger Grosse and Nitish Srivastava

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- Converting linear models into nonlinear models using basis functions (features). $y = \mathbf{w}^T \mathbf{x}$, becomes $y = \mathbf{w}^T \Phi(\mathbf{x})$

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- Converting linear models into nonlinear models using basis functions (features). y = w^Tx, becomes y = w^TΦ(x)

But this raises some questions:

- What if the thing we're trying to predict isn't real-valued or binary-valued?
- What if we don't know the right features Φ?

This week, we cover a much more general learning framework which gets around both of these issues.

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- For the perceptron, we gave a simple add/subtract algorithm which works under an unrealistic "linear separability" assumption.

For most of this course, we will instead write down an objective function and optimize it using a technique called gradient descent.



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Some examples of loss functions we'll learn about later

Setting	Example	Loss function $C(w)$
least-squares regression	predict stock prices	$(y - t)^2$
robust regression	predict stock prices	y - t
classification	predict object category from image	$-\log p(t \mathbf{x})$
generative modeling	model distribution of English sentences	$-\log p(\mathbf{x})$

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Synonyms : Loss Function/Error Function/Cost Function/Objective Function.

Learning \equiv minimizing unhappiness.

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Optimization

Visualizing gradient descent in one dimension: $w \leftarrow w - \epsilon \frac{dC}{dw}$



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Optimization



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Visualizing it in two dimensions is a bit tricker.

- Level sets (or contours): sets of points on which $C(\mathbf{w})$ is constant
- Gradient: the vector of partial derivatives

$$\nabla_{\mathbf{w}} C = \left(\frac{\partial C}{\partial w_1}, \frac{\partial C}{\partial w_2}\right)$$

- points in the direction of maximum increase
- orthogonal to the level set
- The gradient descent updates are opposite the gradient direction.

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Optimization



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Suppose we have a linear regression problem with two training cases and no bias term:

•
$$\mathbf{x}^{(1)} = (1,0), t^{(1)} = 0.5$$

• $\mathbf{x}^{(2)} = (0,3), t^{(2)} = 0$

Recall that the objective function is

$$C(\mathbf{w}) = \frac{1}{2} (\mathbf{w}^{\mathsf{T}} \mathbf{x}^{(1)} - t^{(1)})^2 + \frac{1}{2} (\mathbf{w}^{\mathsf{T}} \mathbf{x}^{(2)} - t^{(2)})^2.$$

- In weight space, sketch the level set of this objective function corresponding to $C(\mathbf{w}) = 1/2$. Draw both axes with the same scale.
 - Hint: Write the equation $C(\mathbf{w}) = 1/2$ explicitly in the form

$$\frac{(w_1-c)^2}{a^2} + \frac{(w_2-d)^2}{b^2} = 1.$$

What geometric object is this, and what do (a, b, c, d) represent?

(a) The point $\mathbf{w} = (1.25, 0.22)$ is on the level set for $C(\mathbf{w}) = 1/2$. Sketch the gradient $\nabla_{\mathbf{w}}C$ at this point.

 \bigcirc Now sketch the gradient descent update if we use a learning rate of 1/2.

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Note: we chose the numbers for this problem so that the ellipse would be axis-aligned. In general, the level sets for linear regression will be ellipses, but they won't be axis-aligned.

- But all ellipses are rotations of axis-aligned ellipses, so the axis-aligned case gives us all the intuition we need.
- You may have learned how to draw non-axis-aligned ellipses in a linear algebra class. If not, don't worry about it.



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- Which weight will change faster: w₁ or w₂? Which one do you want to change faster?



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Note: a more representative picture would show it MUCH more elongated!

Now let's consider a non-linear neuron whose activation is computed as follows:

$$z = \mathbf{w}^T \mathbf{x} = \sum_j w_j x_j$$
 $y = \log(1 + z^2)$

We will use the cost function

$$C(\mathbf{w})=|y-t|.$$

Show how to compute the partial derivative $\partial C / \partial w_1$ using the Chain Rule as follows:

- **(**) Compute the derivative dC/dy. (You may assume $y \neq t$.)
- **2** Express the derivative dC/dz in terms of dC/dy.
- **③** Express the partial derivative $\partial C / \partial w_1$ in terms of dC/dz

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Solution:

$$\frac{\mathrm{d}C}{\mathrm{d}y} = \begin{cases} 1 & \text{if } y > t \\ -1 & \text{if } y < t \end{cases}$$
$$\frac{\mathrm{d}C}{\mathrm{d}z} = \frac{\mathrm{d}y}{\mathrm{d}z}\frac{\mathrm{d}C}{\mathrm{d}y}$$
$$= \frac{2z}{1+z^2}\frac{\mathrm{d}C}{\mathrm{d}y}$$
$$\frac{\partial C}{\partial w_1} = \frac{\partial z}{\partial w_1}\frac{\mathrm{d}C}{\mathrm{d}z}$$
$$= x_1\frac{\mathrm{d}C}{\mathrm{d}z}$$

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$$= \frac{2z}{1+z^2}\frac{\mathrm{d}C}{\mathrm{d}y}$$
$$\frac{\mathrm{d}C}{\mathrm{d}w_1} = \frac{\partial z}{\mathrm{d}w_1}\frac{\mathrm{d}C}{\mathrm{d}z}$$
$$= x_1\frac{\mathrm{d}C}{\mathrm{d}z}$$

Note: If this were a calculus class, you'd do the substitutions to get $\partial C / \partial w_1$ explicitly. We won't do that here, since at this point you've already derived everything you need to implement the computation in Python.

Observe that we compute derivatives going backwards through the computation graph:



This is true in general, not just for neural nets.

This is how we get the term "backpropagation."