Highway Networks and Residual Networks

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Neural Network

• A network connecting numerous neurons

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Neural Network

• A network connecting numerous neurons



Highway Networks and Residual Networks

• Imagine a neural network as a map

Image: A match a ma

- Imagine a neural network as a map
- Imagine a neuron as a place

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• Suppose you (information flow) wants to reach Bakery (neuron B) from City Hall (neuron A), what will you do?

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- You have to follow the path of network!
- What if there is a highway connecting Bakery and City Hall directly?



Allowing direct pass (highway) between neurons in different layers.

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Inputs

Outputs



► < ∃ ►</p>

Original network:

$$z_1 = \sigma \left(\sum_{n=1}^{\infty} w_n^1 x_n + b \right)$$

Image: A match a ma

(1)

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$$z_1 = \sigma \left(\sum_{n=1}^{\infty} w_n^1 x_n + b \right) \tag{1}$$

Image: A match a ma

Highway network:

$$z_1 = T\sigma\left(\sum_{n=1}^{\infty} w_n^1 x_n + b\right) + (1-T)x_1$$
(2)

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Gating function:

$$T = \sigma \left(\sum_{n=1} w'_n x_n + b' \right) \tag{3}$$

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• Remember the shape of sigmoid function.

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• We can set bias b' to negative values such that gating value $T \rightarrow 0$.

Benefits of Highway networks

• Enable training of very deep neural networks (e.g., hundreds of layers)





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"Srivastava, R.K., Greff, K. and Schmidhuber, J., 2015. Highway Networks. arXiv preprint arXiv:1505.00387".

• Motivation: Does depth matter for deep learning?

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"He, K., Zhang, X., Ren, S. and Sun, J., 2015. Deep Residual Learning for Image Recognition. arXiv preprint arXiv:1512.03385".

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• We need new architecture to make depth matter.

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- Suppose you have a plain 2-layer network \mathcal{H} .



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- We need new architecture to make depth matter.
- Suppose you have a plain 2-layer network \mathcal{H} .
- We use a new building block which forces the previous 2-layer \mathcal{F} to learn the residual $\mathcal{H} x$.

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• What we have done?

• What we have done?



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• Based on this building block, we can do some crazy things like...

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ImageNet Classification top-5 error (%)

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PASCAL VOC 2007 Object Detection mAP (%)

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task	2nd-place winner	MSRA	margin (relative)
ImageNet Localization (top-5 error)	12.0	9.0	27%
ImageNet Detection (mAP@.5)	53.6 abs	blute 62.1	16%
COCO Detection (mAP@.5:.95)	33.5	37.3	11%
COCO Segmentation (mAP@.5:.95)	25.1	28.2	12%

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More Results



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input

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